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A.R.C. Technical Report



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Approximate Two-dimensional Aerofoil Theory  
Part IV. The Design of Centre Lines

By

S. GOLDSTEIN, F.R.S

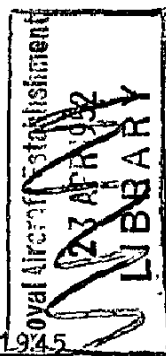
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1952

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24th March, 1945

Summary

Centre lines may be designed from a knowledge of the quantity  $g_1$  introduced in Part II<sup>a</sup>, eqn.(54).  $4g_1$  may be loosely said to give the approximate chordwise distribution of the normal force coefficient  $(p_l - p_u)/(\frac{1}{2}\rho U^2)$  (but loadings should, in fact, be calculated by Approximation III).

In terms of  $g_1$ , the centre line ordinate  $y_c$  is given by

$$y_c = \frac{x(1-x)}{\pi} \int_0^1 \frac{G_1(\xi) - \xi G_1(1)}{\xi(1-\xi)(\xi-x)} d\xi - \frac{1}{4} A_1 \{x \ln x + (1-x) \ln (1-x)\},^*$$

where the principal value of the integral is to be taken,

$$G_1(x) = \int_0^x g_1 dx,$$

and

$$A_1 = \frac{4}{\pi} G_1(1).$$

With

$$A_0 = \frac{1}{\pi} \int_0^1 \frac{G_1(\xi) - \xi G_1(1)}{\xi(1-\xi)} d\xi,$$

$$\frac{dy_c}{dx} - A_0 = \frac{1}{\pi} \int_0^1 \frac{g_1(\xi)}{\xi - x} d\xi,$$

where again the principal value of the integral is to be taken. Also

$$\left(\frac{\pi}{\theta_0} + \frac{1}{2}\right) \sigma_{T, opt} = \pi A = 4 \int_0^1 g_1 dx, \quad \alpha_{opt}$$

\*ln is used for  $\log_e$ .

$$\alpha_{\text{opt}} = A_0 + \frac{1}{2} \left( \frac{2\pi - a_0}{2\pi + a_0} \right) A_1,$$

$$C_{M_0} = - \int_0^1 (4x - 1) g_i(x) dx,$$

$$\beta = \frac{1}{2} A_1 - A_0,$$

$$\varepsilon_c(\theta) = 2 \left[ G_i(x) - \frac{1}{4} A_1 \theta \right] \operatorname{cosec} \theta - A_0,$$

$$\varepsilon'_c(0) = -\frac{1}{2} A_1 - A_0,$$

$$\varepsilon'_c(\theta) = g_i - (A_0 + \varepsilon_c) \cot \theta - \frac{1}{2} A_1 \operatorname{cosec} \theta.$$

It is shown how explicit formulae may be easily built up when  $g_i$  is a polynomial in  $x$  in each of any number of segments of the chord. Explicit formulae are set out for the following cases (with occasional remarks on their use and suggestions for experiment):  $g_i$  quadratic in each of three segments, or in each of two segments, or over the whole chord;  $g_i$  linear in each of three segments (Figs. 1, 2, 3, 4) or in each of two segments (Fig. 5) or over the whole chord (Fig. 6);  $g_i$  constant over the whole chord (Fig. 7);  $g_i$  constant for  $0 \leq x \leq X$  and decreasing linearly to zero for  $X \leq x \leq 1$  (Fig. 8);  $g_i$  constant for  $0 \leq x \leq X$  and parabolic for  $X \leq x \leq 1$ , with  $g_i(1) = g'_i(1) = 0$  (Fig. 10);  $g_i$  discontinuous and constant in each of two segments (Fig. 11).

It is shown how, when the graph of  $g_i$  against  $x$  is composed of straight lines, the solution may always be built up from certain 'basic' solutions, of which the most important are those of Figs. 7 and 8, and, when  $g_i$  is discontinuous, of Fig. 14.

We have occasion to mention a few trite and obvious principles underlying the choice of a particular design of centre line in connection with Figs. 8 and 10 and (for 'suction' aerofoils) Fig. 11.

Extensive tables are given for the centre lines designed according to Figs. 7 and 8.

1. Introduction

In Part III\* we remarked that if we know Approximation I to the velocity  $q$  on both the upper and lower surfaces of an aerofoil in a uniform unlimited stream  $U$ , then we know\*  $g_s$  and  $g_c + g_L$  separately, and that we can design the fairing from a knowledge of  $g_s$  and the centre line from a knowledge of  $g_c + g_L$ ; the ability to design the aerofoil shape from Approximation I to the velocity is sufficient for many purposes. In Part III we also considered briefly the problem of obtaining values of  $g_s$  and  $g_c + g_L$  when the exact pressure or velocity distribution is specified, and we then considered in detail the design of the fairing from a knowledge of  $g_s$ . In this report we shall be concerned with the design of the centre line; this design is actually worked out from a knowledge of the quantity  $g_i$  introduced in Part II, eqn. (54), and related to  $g_c + g_L$  by the equation

$$g_c + g_L = g_i + \frac{1}{2} \left( \frac{1}{a_0} + \frac{1}{2\pi} \right) (C_L - C_{Lopt}) \cot \frac{1}{2}\theta - \frac{1}{2} \left( \frac{1}{a_0} - \frac{1}{2\pi} \right) C_L \tan \frac{1}{2}\theta, \quad \dots(1)$$

where

$$g_L = a_0(\alpha + \beta)$$

and

$$x = \frac{1}{2}(1 - \cos \theta) = \sin^2 \frac{1}{2}\theta^+.$$

... (2)

It is therefore advisable to consider, by way of preface, the determination of  $g_i$ . Since the pressure distribution is specified,  $C_L$  is known; we require also  $C_{Lopt}$  and  $a_0$ . A rounded trailing edge is a stagnation point when  $a_0 = 2\pi$  (more accurately  $2\pi e^{C_0}$ ), and/

\*We use the same notation as in Parts I, II and III.<sup>1,2,3</sup>

<sup>+</sup>More generally, if the  $(C_L, \alpha)$  curve is not a straight line, we replace  $(C_L - C_{Lopt})/a_0$  in (1) by  $\alpha - \alpha_{opt}$ , and  $C_L/a_0$  by  $\alpha + \beta$ , where  $C_{Lopt}$  and  $\alpha_{opt}$  are to be found as the coordinates of the point on the  $(C_L, \alpha)$  curve where

$$\alpha_{opt} + \beta + C_{Lopt}/2\pi = A_1,$$

$A_1$  being the coefficient of  $\cos \theta$  in the cosine Fourier series for  $dy_c/dx$  (as a function of  $\theta$ ) in the range  $0 < \theta < \pi$ .

and the leading edge is a stagnation point when  $C_L = C_{Lopt}$  approximately. When the trailing and leading edges are not stagnation points the values of the velocity at those points determine  $a_0$  and  $C_{Lopt}$ . (We must suppose either that  $a_0$  is specified, or that we are given the correct theoretical pressure for the relevant  $a_0$  right up to, and including, the trailing edge.) If  $C_L$  is small we may consider the given velocity distribution as Approximation II; for large values of  $C_L$  it is necessary, and in any case it is more accurate, to use Approximation III. (Part II, eqn.(67)). The velocities at the leading and trailing edges are briefly considered in Appendix I, where it is shown that they may be expressed in terms of  $C_L$ ,  $g_s$ ,  $a_0$  and  $C_{Lopt}$ , so an estimate of Approximation I carries with it knowledge not only of  $g_s$  and of  $g_c + g_L$ , but also of  $a_0$  and  $C_{Lopt}$ , and therefore of  $g_i$ .

It should be noted that the final value of  $g_i$  must be free from singularities at the leading and trailing edges. In fact

$$\left. \begin{aligned} g_i &= \sum_{n=1}^{\infty} A_n \sin n\theta \\ \frac{dy_c}{dx} &= \sum_{n=0}^{\infty} A_n \cos n\theta, \end{aligned} \right\} \dots(3)$$

where

so  $g_i$  is zero at the leading and trailing edges if  $dy_c/dx$  is free from singularities.

On the linear theory the non-dimensional normal force distribution is given by

$$\frac{p_l - p_u}{\frac{1}{2}\rho U^2} = \left(\frac{a_u}{U}\right)^2 - \left(\frac{a_l}{U}\right)^2 = 4(g_c + g_L), \dots(4)$$

where the suffixes u and l refer to the upper and lower surfaces, respectively. For  $C_L = C_{Lopt}$  and  $a_0 = 2\pi$ , this normal force distribution is therefore given by

$$\frac{p_l - p_u}{\frac{1}{2}\rho U^2} = 4g_i, \dots(5)$$

so  $4g_i$  may be loosely said to give the approximate chordwise loading distribution at the optimum or design  $C_L$ . But loadings should, in fact, be calculated by Approximation III.

## 2. The Quantities to be Calculated

From a knowledge of  $g_i$  we now wish to calculate the centre-line ordinate  $y_c$ , also the no-lift angle  $-\beta$  and the moment coefficient  $C_{M_0}$  at zero lift. In terms of the coefficients  $A_n$ ,  $\beta$  (which is the value of  $g_c$  at  $\theta = \pi$ ) and  $g_c(0)$  are given by

$$\beta = \frac{1}{2} A_1 - A_0, \quad \varepsilon_0(0) = -\frac{1}{2} A_1 - A_0, \quad \dots(6)$$

and  $C_{M_0}$  by

$$C_{M_0} = \frac{1}{4} \pi(A_2 - A_1), \quad \dots(7)$$

so we shall calculate  $A_0, A_1, A_2$ . The 'optimum' lift coefficient is given by

$$\left( \frac{\pi}{a_0} + \frac{1}{2} \right) C_{Lopt} = \pi A_1, \quad \dots(8)$$

and the 'optimum' incidence by

$$\alpha_{opt} = A_0 + \frac{1}{2} \left( \frac{2\pi - a_0}{2\pi + a_0} \right) A_1. \quad \dots(9)$$

When we have completed our approximate design of a cambered aerofoil, we shall probably wish to calculate the velocity distribution for several values of  $C_L$  on Approximation III. In some cases, for rough guidance, Approximation II or even Approximation I may be useful. We therefore repeat here the relevant formulae, in suitable forms.

Approximation I:

$$\frac{q}{U} = 1 + \varepsilon_S + \varepsilon_0 + \varepsilon_L, \quad \dots(10)$$

where  $\varepsilon_S$  was settled in designing the fairing and

$$\varepsilon_0 + \varepsilon_L = \varepsilon_i + \frac{1}{2} \left[ \left( \frac{1}{a_0} + \frac{1}{2\pi} \right) C_L - A_1 \right] \cot \frac{1}{2}\theta - \frac{1}{2} \left( \frac{1}{a_0} - \frac{1}{2\pi} \right) C_L \tan \frac{1}{2}\theta. \quad \dots(11)$$

Approximation II:

$$\begin{aligned} \frac{q}{U} &= \frac{(1 + \frac{1}{2}C_0^2) |\sin \theta|}{(\psi^2 + \sin^2 \theta)^{\frac{1}{2}}} (1 + \varepsilon_S + \varepsilon_0 + \varepsilon_L) \\ &= \frac{(1 + \frac{1}{2}C_0^2) |\sin \theta|}{(\psi^2 + \sin^2 \theta)^{\frac{1}{2}}} (1 + \varepsilon_S + \varepsilon_i) \\ &\pm \frac{1 + \frac{1}{2} C_0^2}{(\psi^2 + \sin^2 \theta)^{\frac{1}{2}}} \left[ \frac{C_L}{2\pi} + \frac{C_L}{a_0} \cos \theta - \frac{1}{2} A_1 (1 + \cos \theta) \right]. \quad \dots(12) \end{aligned}$$

Approximation/

Approximation III:

$$\frac{q}{U} = \frac{e^{C_0} (1 + \varepsilon')}{(\psi^2 + \sin^2 \theta)^{\frac{1}{2}}} \left[ \left( 1 - \frac{C_L^2}{a_0^2} \right)^{\frac{1}{2}} \sin (\theta + \varepsilon - \beta) + \frac{C_L}{a_0} \cos (\theta + \varepsilon - \beta) + \frac{C_L e^{-C_0}}{2\pi} \right] \dots(13)$$

If the suffix  $u$  refers to the upper surface and  $l$  to the lower surface, then

$$\psi_u = \psi_s + \psi_c, \quad \psi_l = \psi_s - \psi_c, \quad \dots(14)$$

$$\varepsilon_u = \varepsilon_c + \varepsilon_s, \quad \varepsilon_l = \varepsilon_c - \varepsilon_s, \quad \dots(15)$$

$$\varepsilon'_u = \varepsilon'_s + \varepsilon'_c, \quad \varepsilon'_l = \varepsilon'_s - \varepsilon'_c, \quad \dots(16)$$

and it must be remembered that  $\theta$  is positive on the upper and negative on the lower surface. We showed how to calculate  $C_0$ ,  $\psi_s$ ,  $\varepsilon_s$ ,  $\varepsilon'_s$  in Part III; we must here consider the calculation of  $\psi_c$ ,  $\varepsilon_c$ ,  $\varepsilon'_c$ . We find  $\psi_c$  at once from  $y_c$ , since

$$\psi_c = 2y_c \operatorname{cosec} \theta; \quad \dots(17)$$

but it is more convenient to find  $\varepsilon_c$ ,  $\varepsilon'_c$  from  $g_i$  by means of the equation

$$\varepsilon'_c + (\varepsilon_c - \beta) \cot \theta = g_c = g_i - \frac{1}{2} A_1 \cot \frac{1}{2} \theta \dots(18)$$

### 3. General Formulae

The analysis is most conveniently carried out, in the main, in terms of  $x$ , as in Part I, and not in terms of  $\theta$ , as in Parts II and III. Consequently it is most convenient to regard  $g_i$  as a function of  $x$ , and to consider that  $g_i(x)$  is given; when we wish to write  $g_i$  as a function of  $\theta$  we must write  $g_i(\sin^2 \frac{1}{2} \theta)$  and not  $g_i(\theta)$ . When it is clear what is intended we shall merely write  $g_i$ .

From (3) we see that the Fourier cosine series for  $(dy_c/dx) - A_0$ , considered as a function of  $\theta$ , is conjugate to the Fourier sine series for  $g_i(\sin^2 \frac{1}{2} \theta)$  in  $(0, \pi)$ , so [from Lemma (6) of Part I (Appendix)]

$$\begin{aligned} \frac{dy_c}{dx} - A_0 &= \frac{1}{\pi} P \int_0^\pi \frac{g_i(\sin^2 \frac{1}{2} t) \sin t}{\cos \theta - \cos t} dt \\ &= \frac{1}{\pi} P \int_0^1 \frac{g_i(\xi)}{\xi - x} d\xi \quad \dots(19) \end{aligned}$$



[cf. Ref. 4 and Ref. 8], where P denotes, as usual, that the principal value of the integral is to be taken, and we have made the substitution

$$\xi = \frac{1}{2}(1 - \cos t) = \sin^2 \frac{1}{2}t. \quad \dots(20)$$

The Fourier series in (3) terminate if, and only if,  $g_i$  is equal to  $x^{\frac{1}{2}}(1-x)^{\frac{1}{2}}$  multiplied by a polynomial in  $x$  over the whole range  $0 < x < 1$ . The Fourier series may be used with advantage if they terminate; numerical methods may be used to evaluate the integral in (19), or use may be made of the analytical results of the following sections. The last method is recommended if it is applicable and the Fourier series do not terminate.

When  $(dy_c/dx) - A_0$  has been found, the value of  $y_c - A_0x$  at  $x$  may be obtained by direct integration between the limits 0 and  $x$ ; and since  $y_c = 0$  at  $x = 1$ ,  $-A_0$  is the value of  $y_c - A_0x$  at  $x = 1$ .

In actual examples  $y_c$  and  $A_0$  may be calculated in this way, but it is desirable to have available explicit formulae for them. We shall find such formulae after considering the calculation of  $A_1, A_2, \varepsilon_c, \varepsilon_c'$ .

We write

$$G_1(x) = G_1\left(\frac{1}{2} \sin^2 \theta\right) = \frac{1}{2} \int_0^\theta g_1 \sin \theta \, d\theta = \int_0^x g_1 \, dx. \quad \dots(21)$$

It follows immediately from (3) that

$$A_1 = \frac{2}{\pi} \int_0^\pi g_1 \sin \theta \, d\theta = \frac{4}{\pi} G_1(1), \quad \dots(22)$$

and

$$A_2 = \frac{2}{\pi} \int_0^\pi g_1 \sin 2\theta \, d\theta = \frac{8}{\pi} \int_0^1 g_1(1-2x) \, dx, \quad \dots(23)$$

so from (7) and (8)

$$\left(\frac{\pi}{a_0} + \frac{1}{2}\right) C_{Lopt} = 4 \int_0^1 g_1 \, dx,$$

$$C_{M_0} = - \int_0^1 g_1(x)(4x-1) \, dx. \quad \dots(24)$$

From/

From (18) and (6) the equation for  $\varepsilon_c$  is

$$\begin{aligned} \frac{d}{d\theta} (\varepsilon_c \sin \theta) &= g_i \sin \theta + \beta \cos \theta - \frac{1}{2} A_1 (1 + \cos \theta) \\ &= g_i \sin \theta - A_0 \cos \theta - \frac{1}{2} A_1. \end{aligned} \quad \dots(25)$$

Hence

$$\varepsilon_c \sin \theta = 2G_i - \frac{1}{2} A_1 \theta - A_0 \sin \theta, \quad \dots(26)$$

and

$$\varepsilon_c = 2 \left[ G_i(x) - \frac{1}{4} A_1 \theta \right] \operatorname{cosec} \theta - A_0. \quad \dots(27)$$

The limits of this expression for  $\varepsilon_c$  as  $x \rightarrow 0$  and  $x \rightarrow 1$  yield the values of  $\varepsilon_c(0)$  and  $\beta$  given by eqn.(6).

From (18), or by differentiation of (27), we find that

$$\begin{aligned} \varepsilon_c'(\theta) &= g_i - (A_0 + \varepsilon_c) \cot \theta - \frac{1}{2} A_1 \operatorname{cosec} \theta \\ &= g_i - 2 \operatorname{cosec}^2 \theta \left[ G_i(x) \cos \theta - \frac{1}{4} A_1 \theta \cos \theta + \frac{1}{4} A_1 \sin \theta \right] \end{aligned} \quad \dots(28)$$

The limits of (28) as  $\theta \rightarrow 0$  and  $\theta \rightarrow \pi$  are given by

$$\varepsilon_c'(0) = \frac{1}{2} g_i(0), \quad \varepsilon_c'(\pi) = \frac{1}{2} g_i(1). \quad \dots(29)$$

These results refer to  $0 < \theta < \pi$ ;  $\varepsilon_c$  is even and  $\varepsilon_c'$  is odd;  $\varepsilon_c'$  is discontinuous at  $\theta = 0$  if  $g_i(0)$  is not zero and at  $\theta = \pi$  if  $g_i(1)$  is not zero. In practice it is probably best to fair off  $\varepsilon_c'(\theta)$  to 0 at  $\theta = 0$  and  $\theta = \pi$ .

We now return to the calculation of  $A_0$  and  $y_c$ . From Part II, eqns. (18) and (19), if

$$\psi_c = \sum_{n=1}^{\infty} D_n \sin n\theta \quad \dots(30)$$

then

$$\varepsilon_c = - \sum_{n=1}^{\infty} D_n \cos n\theta. \quad \dots(31)$$

Hence, in the first place

$$\int_0^{\pi} \varepsilon_c(\theta) d\theta = 0, \quad \dots(32)$$

so/

so from (27),

$$A_0 = \frac{2}{\pi} \int_0^{\pi} \frac{G_1(\sin^2 \frac{1}{2}t) - \frac{1}{4} A_1 t}{\sin t} dt. \quad \dots(33)$$

From Lemma 1, Appendix II,

$$\int_0^{\pi} \frac{\frac{1}{8}\pi A_1(1 - \cos t) - A_1 t}{\sin t} dt = 0, \quad \dots(34)$$

so

$$\begin{aligned} A_0 &= \frac{2}{\pi} \int_0^{\pi} \frac{G_1(\sin^2 \frac{1}{2}t) - \frac{1}{8}\pi A_1(1 - \cos t)}{\sin t} dt \\ &= \frac{1}{\pi} \int_0^1 \frac{G_1(\xi) - \zeta G_1(1)}{\xi(1 - \xi)} d\xi. \quad \dots(35) \end{aligned}$$

Secondly, it follows from (30) and (31) (by Lemma 6 of Part I) that

$$\psi_c(\theta) = \frac{\sin \theta}{\pi} P \int_0^{\pi} \frac{\varepsilon_c(t)}{\cos \theta - \cos t} dt.$$

Hence, from (27),

$$\psi_c(\theta) = \frac{2 \sin \theta}{\pi} P \int_0^{\pi} \frac{G_1(\sin^2 \frac{1}{2}t) - \frac{1}{4} A_1 t}{\sin t(\cos \theta - \cos t)} dt, \quad \dots(36)$$

since

$$P \int_0^{\pi} \frac{dt}{\cos \theta - \cos t} = 0. \quad \dots(37)$$

Therefore

$$y_c = \frac{1}{2}\psi_c \sin \theta = \frac{\sin^2 \theta}{\pi} P \int_0^{\pi} \frac{G_1(\sin^2 \frac{1}{2}t) - \frac{1}{4} A_1 t}{\sin t(\cos \theta - \cos t)} dt. \quad \dots(38)$$

From Lemma 2, Appendix II,

$$\begin{aligned} \frac{\sin^2 \theta}{\pi} P \int_0^{\pi} \frac{\frac{1}{8}\pi A_1(1 - \cos t) - \frac{1}{4} A_1 t}{\sin t(\cos \theta - \cos t)} &= -\frac{1}{3} A_1 \left\{ (1 - \cos \theta) \ln \frac{1}{2}(1 - \cos \theta) \right. \\ &\quad \left. + (1 + \cos \theta) \ln \frac{1}{2}(1 + \cos \theta) \right\}^* \dots(39) \end{aligned}$$

Hence/

\*ln is used for log<sub>e</sub>.

Hence

$$\begin{aligned}
 y_c &= \frac{\sin^2 \theta}{\pi} P \int_0^\pi \frac{G_i(\sin^2 \frac{1}{2}t) - \frac{1}{8}\pi A_1(1 - \cos t)}{\sin t(\cos \theta - \cos t)} dt \\
 &\quad - \frac{1}{8} A_1 \left\{ (1 - \cos \theta) \ln \frac{1}{2}(1 - \cos \theta) + (1 + \cos \theta) \ln \frac{1}{2}(1 + \cos \theta) \right\} \\
 &= \frac{x(1-x)}{\pi} P \int_0^1 \frac{G_i(\xi) - \xi G_i(1)}{\xi(1-\xi)(\xi-x)} d\xi - \frac{1}{8} A_1 \left\{ x \ln x + (1-x) \ln(1-x) \right\}.
 \end{aligned}$$

... (40)

Equations (35) and (40) are in a suitable form for the direct computation of  $A_0$  and  $y_c$ .

4. Basis for Explicit Formulæ when  $g_i$  is a Polynomial in  $x$  in Each of any Number of Segments.

We have completed our investigation of the general equations, and proceed to show how the various quantities required may be calculated analytically in special examples. It is clear from the form of our general equations that the whole mathematical apparatus of the Appendix to Part I is at our disposal, so results may be obtained analytically for a wide variety of algebraical formulations of  $g_i$ ; it is probably sufficient for the present, however, to consider that, with the chord divided into any number of segments, in each segment  $g_i$  is represented by a polynomial in  $x$ . Then we can build up the complete expressions for any such case from appropriate multiples of the contributions corresponding to a term in  $x^n$  in the expression for  $g_i$  in the interval  $x_{r-1} \leq x \leq x_r$ . For such a term the contribution to

$$\left. \begin{aligned}
 G_i(x) &= 0 \quad \text{for } 0 \leq x \leq x_{r-1} \\
 &= \frac{1}{n+1} \left( x^{n+1} - x_{r-1}^{n+1} \right) \quad \text{for } x_{r-1} \leq x \leq x_r \\
 &= \frac{1}{n+1} \left( x_r^{n+1} - x_{r-1}^{n+1} \right) \quad \text{for } x_r \leq x \leq 1
 \end{aligned} \right\} \dots (41)$$

The contribution to

$$A_1 = \frac{4}{\pi(n+1)} \left( x_r^{n+1} - x_{r-1}^{n+1} \right). \quad \dots (42)$$

It follows from (41) and Lemma 12 of Part I (Appendix) that the contribution to

$$A_0 = \frac{1}{\pi(n+1)} \left\{ \left(1 - x_{r-1}^{n+1}\right) \ln \left(1 - x_{r-1}\right) - \left(1 - x_r^{n+1}\right) \ln \left(1 - x_r\right) \right. \\ \left. - x_r^{n+1} \ln x_r + x_{r-1}^{n+1} \ln x_{r-1} - \sum_{m=1}^n \frac{x_r^m - x_{r-1}^m}{m} \right\}, \quad \dots(43)$$

the last term being omitted if  $n = 0$ . The contribution to  $\beta$  then follows from (6), and to  $C_{\text{lopt}}$  and  $\alpha_{\text{opt}}$  from (8) and (9); the contribution to

$$- C_{M_0} = \frac{4}{n+2} \left(x_r^{n+2} - x_{r-1}^{n+2}\right) - \frac{1}{n+1} \left(x_r^{n+1} - x_{r-1}^{n+1}\right) \dots(44)$$

From (40) and Lemma (9) Part I (Appendix) we find that the contribution to

$$y_c = \frac{1}{\pi(n+1)} \left\{ \left(x_r^{n+1} - x_{r-1}^{n+1}\right) \ln |x - x_r| - \left(x_r^{n+1} - x_{r-1}^{n+1}\right) \ln |x - x_{r-1}| \right. \\ \left. - x \left[ \left(1 - x_r^{n+1}\right) \ln \left(1 - x_r\right) - \left(1 - x_{r-1}^{n+1}\right) \ln \left(1 - x_{r-1}\right) \right] \right. \\ \left. + (1 - x) \left[ x_r^{n+1} \ln x_r - x_{r-1}^{n+1} \ln x_{r-1} \right] \right. \\ \left. - x(1 - x) \sum_{s=0}^{n-2} x^s \sum_{m=1}^{n-s-1} \frac{x_r^m - x_{r-1}^m}{m} \right\} \quad \dots(45)$$

For  $n = 0$  and  $n = 1$  the last term inside the  $\{\}$  is to be omitted; for other values of  $n$  it may be expressed in the alternative form

$$\sum_{s=2}^n x^s \frac{x_r^{n-s+1} - x_{r-1}^{n-s+1}}{n - s + 1} \dots x \sum_{m=1}^{n-1} \frac{x_r^m - x_{r-1}^m}{m} \quad \dots(46)$$

The contribution to  $\varepsilon_c(\theta)$  is given by (27) and to  $\varepsilon_c(0)$  by (6); the contribution to  $c'_c(\theta)$  is similarly given by (28) with the contribution to

$$\left. \begin{aligned} \varepsilon_1 &= 0 && \text{for } 0 < x < x_{r-1} \\ &= x^n && \text{for } x_{r-1} < x < x_r \\ &= 0 && \text{for } x_r < x < 1. \end{aligned} \right\} \quad \dots(47)$$

We may note that, from (19) and Lemma 12 of Part I (Appendix), the contribution to

$$\frac{dy_c}{dx} - A_0 = \frac{1}{\pi} \left\{ x^n \ln \left| \frac{x - x_r}{x - x_{r-1}} \right| + \sum_{m=0}^{n-1} x^m \frac{x_r^{n-m} - x_{r-1}^{n-m}}{n - m} \right\}, \dots(48)$$

the last term being omitted if  $n = 0$ , and this result may be verified by direct differentiation of (45).

5. Explicit Results when  $g_i$  is Quadratic in  $x$  in Each of Three Segments.

We now set out explicit results when, with the chord divided into three segments,  $g_i$  is expressible as a quadratic in  $x$  in each of them, viz.

$$\left. \begin{aligned} g_i &= a_0 + a_1 x + a_2 x^2 \quad \text{for } 0 \leq x \leq X_1 \\ &= b_0 + b_1 x + b_2 x^2 \quad \text{for } X_1 \leq x \leq X_2 \\ &= c_0 + c_1 x + c_2 x^2 \quad \text{for } X_2 \leq x \leq 1 \end{aligned} \right\} \dots(49)$$

Write

$$a_r - b_r = k_r, \quad b_r - c_r = l_r \quad (r = 0, 1, 2). \dots(50)$$

Then

$$\left. \begin{aligned} G_i(x) &= a_0 x + \frac{1}{2} a_1 x^2 + \frac{1}{3} a_2 x^3 \quad \text{for } 0 \leq x \leq X_1 \\ &= b_0 x + \frac{1}{2} b_1 x^2 + \frac{1}{3} b_2 x^3 + k_0 X_1 + \frac{1}{2} k_1 X_1^2 + \frac{1}{3} k_2 X_1^3 \quad \text{for } X_1 \leq x \leq X_2 \\ &= c_0 x + \frac{1}{2} c_1 x^2 + \frac{1}{3} c_2 x^3 + k_0 X_1 + \frac{1}{2} k_1 X_1^2 + \frac{1}{3} k_2 X_1^3 + l_0 X_2 + \frac{1}{2} l_1 X_2^2 \\ &\quad + \frac{1}{3} l_2 X_2^3 \quad \text{for } X_2 \leq x \leq 1. \end{aligned} \right\} \dots(51)$$

$$A_1 = \frac{4}{\pi} G_i(1) = \frac{4}{\pi} \left\{ c_0 + \frac{1}{2} c_1 + \frac{1}{3} c_2 + k_0 X_1 + \frac{1}{2} k_1 X_1^2 + \frac{1}{3} k_2 X_1^3 + l_0 X_2 + \frac{1}{2} l_1 X_2^2 + \frac{1}{3} l_2 X_2^3 \right\}; \dots(52)$$

$$\begin{aligned} A_2 &= -\frac{1}{\pi} \left\{ \left[ k_0(1 - X_1) + \frac{k_1}{2} (1 - X_1^2) + \frac{k_2}{3} (1 - X_1^3) \right] \ln(1 - X_1) \right. \\ &\quad + \left[ l_0(1 - X_2) + \frac{l_1}{2} (1 - X_2^2) + \frac{l_2}{3} (1 - X_2^3) \right] \ln(1 - X_2) \\ &\quad + \left[ k_0 X_1 + \frac{k_1}{2} X_1^2 + \frac{k_2}{3} X_1^3 \right] \ln X_1 \\ &\quad + \left[ l_0 X_2 + \frac{l_1}{2} X_2^2 + \frac{l_2}{3} X_2^3 \right] \ln X_2 \\ &\quad \left. + \left( \frac{k_1}{2} + \frac{k_2}{3} \right) X_1 + \frac{k_2}{6} X_1^2 + \left( \frac{l_1}{2} + \frac{l_2}{3} \right) X_2 + \frac{l_2}{6} X_2^2 + \frac{c_1 + c_2}{2} \right\}; \dots(53) \end{aligned}$$

y✓

$$\begin{aligned}
 y_c = & \frac{1}{\pi} \left\{ \left[ k_0(x - X_1) + \frac{1}{2}k_1(x^2 - X_1^2) + \frac{1}{3}k_2(x^3 - X_1^3) \right] \ln |x - X_1| \right. \\
 & + \left[ l_0(x - X_2) + \frac{1}{2}l_1(x^2 - X_2^2) + \frac{1}{3}l_2(x^3 - X_2^3) \right] \ln |x - X_2| \\
 & - \left[ a_0x + \frac{1}{2}a_1x^2 + \frac{1}{3}a_2x^3 \right] \ln x \\
 & - \left[ c_0(1 - x) + \frac{1}{2}c_1(1 - x^2) + \frac{1}{3}c_2(1 - x^3) \right] \ln (1 - x) \\
 & + \frac{1}{3} \left[ k_2X_1 + l_2X_2 + c_2 \right] x^2 \\
 & + \left[ \pi A_0 + \frac{k_1}{2} X_1 + \frac{k_2}{6} X_1^2 + \frac{l_1}{2} X_2 + \frac{l_2}{6} X_2^2 + \frac{c_1}{2} + \frac{c_2}{6} \right] x \\
 & + (k_0X_1 + \frac{1}{2}k_1X_1^2 + \frac{1}{3}k_2 X_1^3) \ln X_1 \\
 & \left. + (l_0X_2 + \frac{1}{2}l_1X_2^2 + \frac{1}{3}l_2X_2^3) \ln X_2 \right\}; \quad \dots(54)
 \end{aligned}$$

$$\begin{aligned}
 \frac{dy_c}{dx} - A_0 = & \frac{1}{\pi} \left\{ (k_0 + k_1x + k_2x^2) \ln |x - X_1| + (l_0 + l_1x + l_2x^2) \ln |x - X_2| \right. \\
 & - (a_0 + a_1x + a_2x^2) \ln x + (c_0 + c_1x + c_2x^2) \ln (1 - x) \\
 & + x(k_2X_1 + l_2X_2 + c_2) + k_1X_1 + \frac{1}{2}k_2X_1^2 + l_1X_2 \\
 & \left. + \frac{1}{2}l_2X_2^2 + c_1 + \frac{1}{2}c_2 \right\}; \quad \dots(55)
 \end{aligned}$$

$$\begin{aligned}
 -C_{M_0} = & k_2X_1^4 + l_2X_2^4 + \frac{1}{3}X_1^3(4k_1 - k_2) + \frac{1}{3}X_2^3(4l_1 - l_2) \\
 & + X_1^2(2k_0 - \frac{1}{2}k_1) + X_2^2(2l_0 - \frac{1}{2}l_1) - k_0X_1 - l_0X_2 \\
 & + c_0 + \frac{5}{6}c_1 + \frac{2}{3}c_2. \quad \dots(56)
 \end{aligned}$$

With the values of  $\epsilon_1$ ,  $G_1$ ,  $A_1$  and  $A_0$  above,  $\beta$  and  $\epsilon_c(0)$  are given by (6),  $C_{Lopt}$  and  $\alpha_{opt}$  by (8) and (9),  $\epsilon_c(\theta)$  by (27), and  $\epsilon'_c(\theta)$  by (28).

$y_c$  is zero at  $x = 0$  and  $x = 1$ , but  $dy_c/dx$  is logarithmically infinite at  $x = 0$  if  $g(0) \neq 0$ , and at  $x = 1$  if  $g(1) \neq 0$ ; as we have already remarked,  $\epsilon'_c(\theta)$  is discontinuous at  $\theta = 0$  if  $g(0) \neq 0$ , and at  $\theta = \pi$  if  $g(1) \neq 0$ , though in practice it is probably best to fair off  $\epsilon'_c(\theta)$  to 0 at  $\theta = 0$  and  $\theta = \pi$ .

At/

At  $X_1$  and  $X_2$ ,  $G_1, y_c, \varepsilon_c$  are continuous whether  $g_i$  is continuous or not; but if  $g_i$  is not continuous,  $dy_c/dx$  is logarithmically infinite and  $\varepsilon'_c$  finitely discontinuous (so that the velocity  $q$  is finitely discontinuous on Approximation III); similarly, if  $g_i$  is continuous but  $g'_i$  discontinuous,  $d^2y_c/dx^2$  and the curvature of the aerofoil centre line are logarithmically infinite, with  $\varepsilon''_c(\theta)$ , and therefore the velocity gradient along the aerofoil surface, finitely discontinuous.

The results for many special cases may be written down at once from the results of this section.

6.  $g_i$  Quadratic in Each of Two Segments, or Quadratic over the Whole Chord

If

$$\left. \begin{aligned} g_i &= a_0 + a_1x + a_2x^2 \quad \text{for } 0 \leq x \leq X_1 \\ &= b_0 + b_1x + b_2x^2 \quad \text{for } X_1 \leq x \leq 1, \end{aligned} \right\} \dots(57)$$

we put

$$c_r = b_r, \quad l_r = 0 \quad (r = 0, 1, 2)$$

in eqns. (49) - (56) above.

If

$$g_i = a_0 + a_1x + a_2x^2 \quad \text{for } 0 \leq x \leq 1, \quad \dots(58)$$

we put

$$c_r = b_r = a_r, \quad l_r = k_r = 0 \quad (r = 0, 1, 2)$$

in eqns. (49) - (56).

7.  $g_i$  Linear in Each of Three Segments, or Linear in Each of Two Segments

Explicit results have been worked out when  $g_i$  is linear in each of three segments (with or without discontinuities: Figs. 1, 2, 3, 4) or in each of two segments (Fig. 5). Since the algebra is complicated, it has been thought worth while to put the results on record; but since they are likely to be used only rarely they have been relegated to Appendix III.

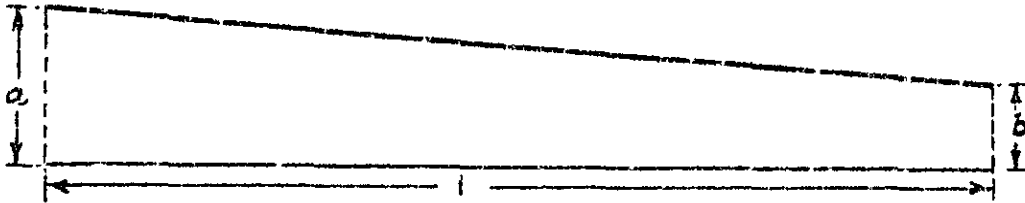
Figures/



8.  $g_i$  Linear Over the Whole Chord

If  $g_i$  is linear throughout  $0 \leq x \leq 1$ ,  $g_i(0) = a$ ,  
 $g_i(1) = b$  (Fig. 6),

FIG. 6



then

$$g_i(x) = a(1-x) + bx \quad (0 \leq x \leq 1);$$

$$G_i(x) = a \left( x - \frac{x^2}{2} \right) + \frac{bx^2}{2} \quad (0 \leq x \leq 1);$$

$$A_1 = \frac{2}{\pi} (a + b);$$

$$A_0 = \frac{1}{2\pi} (a - b);$$

$$y_c = -\frac{a}{2\pi} \left\{ (1-x)^2 \ln(1-x) + (2x-x^2) \ln x \right\}$$

$$-\frac{b}{2\pi} \left\{ (1-x^2) \ln(1-x) + x^2 \ln x \right\};$$

$$\frac{dy_c}{dx} - A_0 = \frac{a}{\pi} \left\{ (1-x) \ln \frac{1-x}{x} - 1 \right\} + \frac{b}{\pi} \left\{ x \ln \frac{1-x}{x} + 1 \right\};$$

$$-C_{M_0} = \frac{1}{6} \{ a + 5b \};$$

$$\beta = \frac{1}{2\pi} (a + 3b);$$

$$\frac{\pi}{a_0}$$

FIG. 1.

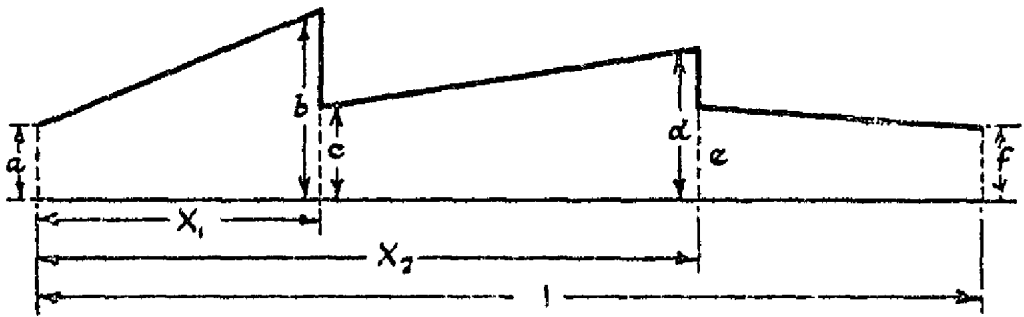


FIG. 2.

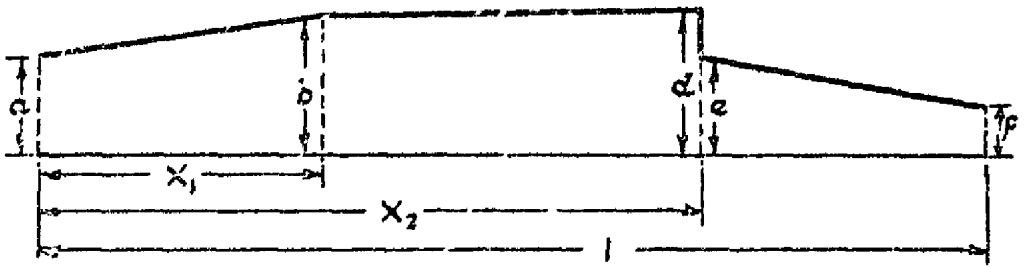


FIG. 3.

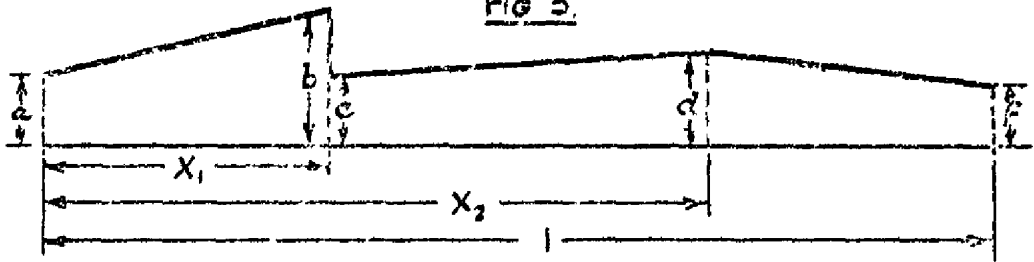


FIG. 4.

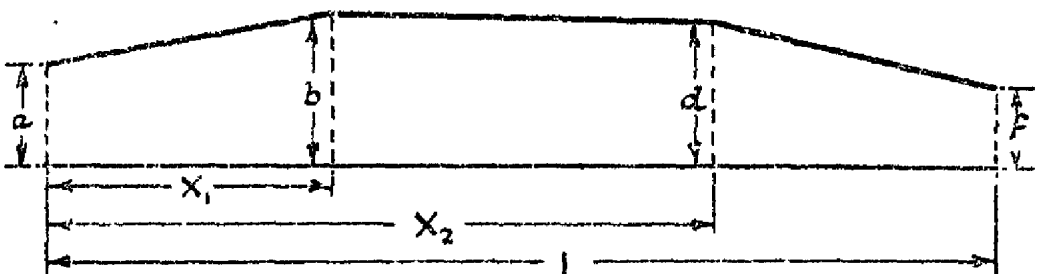
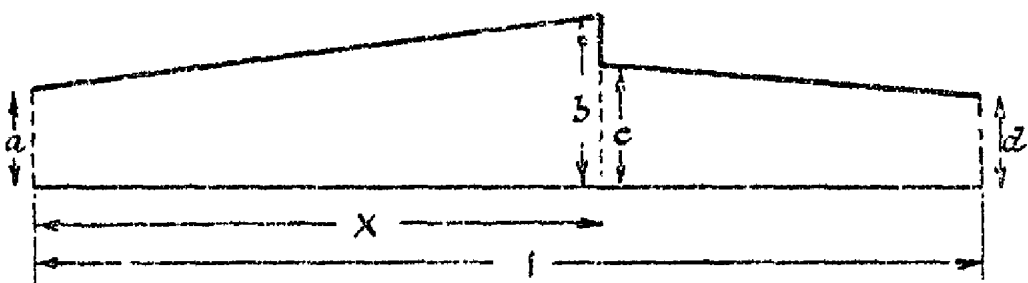


FIG. 5.



$$\left( \frac{\pi}{a_0} + \frac{1}{2} \right) C_{Lopt} = 2(a + b);$$

$$\alpha_{opt} = \frac{a - b}{2\pi} + \left( \frac{2\pi - a_0}{2\pi + a_0} \right) \left( \frac{a + b}{\pi} \right);$$

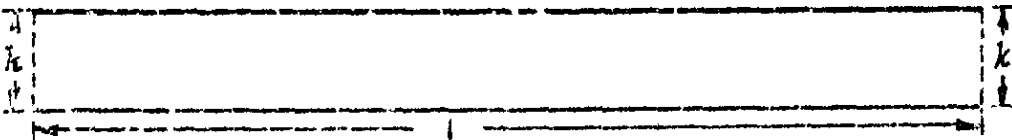
$$\varepsilon_c(0) = -\frac{1}{2\pi} (3a + b).$$

For  $\varepsilon_c(\theta)$  and  $\varepsilon'_c(\theta)$  see (27) and (28).

9.  $g_1$  Constant Over the Whole Chord

If in the last section we put  $a = b = k$  (Fig. 7), we obtain

Fig 7



the results for a constant approximate distribution of normal load; these results have been given by a number of authors<sup>5, 6, 7, 8</sup>

$$y_c = -\frac{k}{\pi} \left\{ (1-x) \ln(1-x) + x \ln x \right\}$$

$$= -0.73293560 k \left\{ (1-x) \log_{10}(1-x) + x \log_{10} x \right\};$$

$$\frac{dy_c}{dx} = \frac{k}{\pi} \ln \frac{1-x}{x};$$

$$-C_{M_0} = k = \frac{1}{4} \left( \frac{\pi}{a_0} + \frac{1}{2} \right) C_{Lopt},$$

so if  $a_0 = 2\pi$ ,

$$-\frac{C_{M_0}}{C_{Lopt}} = \frac{1}{4}.$$

Also/

Also

$$\beta = \frac{2k}{\pi} \left( = \frac{C_{Lopt}}{2\pi} \text{ for } \alpha_0 = 2\pi \right),$$

$\alpha_{opt}$  is zero for  $\alpha_0 = 2\pi$ ,  $\varepsilon_c(0) = -2k/\pi$ , and  $\varepsilon_c(\theta)$ ,  $\varepsilon'_c(\theta)$  are given by (27) and (28) with  $g_i = k$ ,  $G_i = kx$ ,  $A_1 = 4k/\pi$ ,  $A_0 = c$ , i.e.

$$\varepsilon_c(\theta) = 2k \left[ x - \frac{\theta}{\pi} \right] \operatorname{cosec} \theta,$$

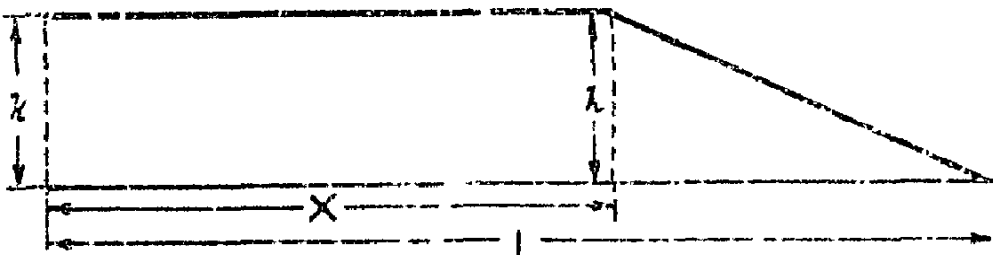
$$\varepsilon'_c(\theta) = k - \varepsilon_c \cot \theta - \frac{2k}{\pi} \operatorname{cosec} \theta.$$

10.  $g_i$  Constant for  $0 < x < X$ , and Decreasing Linearly to Zero for  $X < x < 1$

For low-drag aerofoils it is customary to use centre lines such that  $g_i$  is constant from the leading edge to some value  $X$  of  $x$ , usually chosen to coincide with the design position of maximum suction on the fairing. It may be shown that such centre lines lead to larger  $C_L$ -ranges than any others. An important set of such centre lines is obtained<sup>8,9</sup> if  $g_i$  decreases linearly to zero between  $x = X$  and  $x = 1$ ; but over the rear portion of the aerofoil it is probable that  $g_i$  may sometimes be varied with advantage, particularly with regard to the resultant value of  $C_{M_0}$ , and other shapes of the graph of  $g_i$  between  $X$  and 1 will be considered later.

For the shape of graph here to be considered (Fig. 8)

Fig 8.



$g_i/$

$$\begin{aligned} g_i &= k \quad (0 \leq x \leq X), \\ &= k \frac{1-x}{1-X} \quad (X \leq x \leq 1). \end{aligned}$$

We put  $a = b = k$ ,  $b - c = 0$ ,  $d = 0$  in the formulae of the second section of Appendix III, and we find that

$$\begin{aligned} G_i(x) &= kx \quad (0 \leq x \leq X), \\ &= -k \frac{(X^2 - 2x + x^2)}{2(1-X)} \quad (X \leq x \leq 1); \end{aligned}$$

$$A_1 = \frac{2k}{\pi} (1 + X);$$

$$A_0 = \frac{k}{\pi} \left\{ \frac{1}{2} + \frac{X^2}{2(1-X)} \ln X - \frac{1-X}{2} \ln(1-X) \right\};$$

$$\begin{aligned} y_0 &= \frac{k}{2\pi} \left\{ \frac{(x-X)^2}{1-X} \ln|x-X| - \frac{(1-x)^2}{1-X} \ln(1-x) - 2x \ln x \right. \\ &\quad \left. - x(1-X) \ln(1-X) - (1-x) \frac{X^2}{1-X} \ln X \right\} \end{aligned}$$

$$\begin{aligned} \frac{dy_0}{dx} &= \frac{k}{\pi} \left\{ \frac{x-X}{1-X} \ln|x-X| + \frac{1-x}{1-X} \ln(1-x) - \ln x - \frac{1}{2} \right. \\ &\quad \left. + \frac{X^2}{2(1-X)} \ln X - \frac{1-X}{2} \ln(1-X) \right\} \end{aligned}$$

where

$$\left( \frac{\pi}{a_0} + \frac{1}{2} \right) C_{Lopt} = 2k(1+X).$$

Also

$$-C_{M_0} = \frac{k}{6} (4X^2 + X + 1),$$

so that, for  $a_0 = 2\pi$ ,

$$-\frac{C_{M_0}}{C_{Lopt}} = \frac{4X^2 + X + 1}{12(1+X)},$$

while

$$\beta = \frac{k}{\pi} \left\{ \frac{1}{2} + X - \frac{X^2}{2(1-X)} \ln X + \frac{1-X}{2} \ln(1-X) \right\}.$$

With/

With the values of  $A_1, A_0, g_i, G_i$  above,  $\alpha_{opt}$  is then given by (9),  $\varepsilon_c(0)$  by (6),  $\varepsilon_c(\theta)$ ,  $\varepsilon'_c(\theta)$  by (27) and (28) respectively.

For the purposes of computation the equation for  $y_c$  is written in the form

$$y_c = K_0 \left\{ (x - X)^2 \log_{10} |x - X| - (1 - x)^2 \log_{10} (1 - x) \right\} - K_1 x \log_{10} x + K_2 x + K_3.$$

For a fixed  $X$ , the quantities  $k, A_0, A_1, \beta, C_{M_0}, \alpha_{opt}$  (if  $a_0$  is fixed),  $y_c, g_i, G_i, \psi_c, \varepsilon_c, \varepsilon'_c$  are all proportional to

$$\left( \frac{\pi}{a_0} + \frac{1}{2} \right) C_{Lopt}.$$

In Table I, the coefficients  $K_0, K_1, K_2, K_3$  in the expression for  $y_c$ , together with  $k, A_0, \beta, C_{M_0}$  and  $\varepsilon_c(0)$  are tabulated for  $\left( \frac{\pi}{a_0} + \frac{1}{2} \right) C_{Lopt} = 1$  and various values of  $X$ ;

$$\text{for } \left( \frac{\pi}{a_0} + \frac{1}{2} \right) C_{Lopt} = 1, \quad A_1 = \frac{1}{\pi}.$$

Table II contains values of the ordinates  $y_c$  for  $X = 0.35(0.05)1.0$  and a fairly long list of values of  $x$ ; Table III contains values of  $\psi_c, \varepsilon_c, \varepsilon'_c$ , required for the calculation of  $q/U$  on Approximation III, for the same values of  $X$  and a shorter set of values of  $x$ .

We shall show later how these Tables may be used to build up values for more complicated forms of  $g_i$ .

The Tables were prepared at the National Physical Laboratory, under the supervision of Mrs. Moore, while I was working there.

Some numerical values of the no-lift angle and comparisons with experiment have been given by Jacobs and Abbott<sup>10</sup>. Further comparisons of theory and experiment are to be found in Ref. 11. It should be noted that some disagreement between the measured and calculated values of, say,  $\beta$  and  $C_{M_0}$  is to be expected because of the singularity in the theoretical solution at  $x = 0$  (and at  $x = 1$  if  $X = 1$ ); the exact manner in which the smoothing-away of the singularity in practice will affect the results is difficult to predict, and will probably vary to some extent from model to model. These uncertainties do not seem to be objectionably large in practice.

From the values given in Table I, it appears that, for a given design  $C_L$  (i.e.  $C_{Lopt}$ ),  $-C_{M_0}$  may be inconveniently large, especially if  $X$  is the position of maximum suction on the fairing and this position is required to be fairly far back along the chord. The ratio of  $-C_{M_0}$  to  $C_{Lopt}$  may be decreased by reflexing the centre line towards the trailing edge; it is always preferable to

re-design/

$$\frac{dy_c}{dx} = \frac{k}{\pi} \left\{ \frac{(x-X)(2-X-x)}{(1-X)^2} \ln |x-X| - \ln x + \left( \frac{1-x}{1-X} \right)^2 \ln (1-x) + \frac{x}{1-X} - \frac{2}{3} (1-X) \ln (1-X) + \frac{(3-2X)X^2}{3(1-X)^2} \ln X - \frac{3-X}{3(1-X)} \right\};$$

$$-C_{M_0} = kX^2;$$

$$\left( \frac{\pi}{a_0} + \frac{1}{2} \right) C_{Lopt} = \frac{4k}{3} (1+2X).$$

Hence, for  $a_0 = 2\pi$ ,

$$-\frac{C_{M_0}}{C_{Lopt}} = \frac{3X^2}{4(1+2X)}$$

and

$$\frac{k}{C_{Lopt}} = \frac{3}{4(1+2X)}.$$

For example, for  $X = 0.5$ ,  $k/C_{Lopt} = 0.375$ , compared with 0.333 when  $g_1$  is given by Fig. 8, while  $-C_{M_0}/C_{Lopt} = 0.094$  compared with 0.139; for  $X = 0.6$ ,  $k/C_{Lopt} = 0.341$  and  $-C_{M_0}/C_{Lopt} = 0.123$  compared with 0.3125 and 0.158, respectively. There is therefore a fair reduction in  $-C_{M_0}$  at the expense of a quite small increase in  $k$ ; however, the increased negative pressure gradient just aft of  $x = X$  in these designs will certainly lead to a somewhat thicker boundary layer over the rear of the aerofoil, and, in spite of the decrease of the gradient towards the trailing edge, freedom from danger of turbulent boundary-layer separation may require a somewhat thinner aerofoil for the same value of  $X$ ; it is also possible that separation at the stall may not start at the trailing edge, so the effect on stalling characteristics would have to be investigated. It may, however, be worth while to test an aerofoil with a centre line designed as here described.

## 12. $g_1$ Discontinuous and Constant in Each of Two Segments

On an aerofoil specially designed for suction, there would appear to be no objection to having  $g_1$  discontinuous, so long as the position of the discontinuity is the same as that in the velocity distribution over the fairing (uncambered aerofoil). With such a discontinuity we may, within quite wide limits, obtain any specified value of  $-C_{M_0}/C_{Lopt}$  by adjusting the ratio of the loading in front of and behind the discontinuity. Negative loading

over/

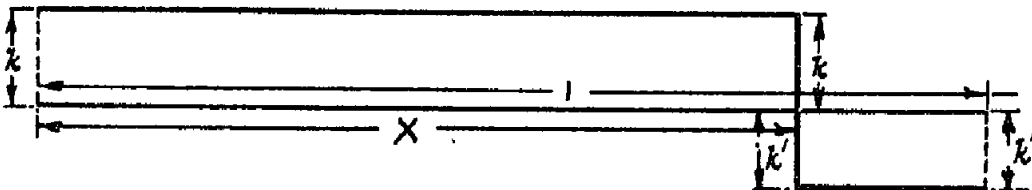
over the rear portion of the chord will usually be necessary to obtain values of  $-C_{M_0}/C_{Lopt}$ , but the danger of turbulent boundary layer separation certainly does not arise, since the whole point of the design of such aerofoils is to concentrate the pressure recovery (fall in velocity) at one chordwise station on each surface, where a slot is cut and boundary-layer suction applied. There will, however, be a rise in the maximum value of  $g_i$ , with a consequent rise in the maximum value of the velocity on the surface and decrease in the theoretical critical speed for compressibility effects. Since the most important application of the suction principle is likely, for some time to come at any rate, to be to thick aerofoils for aeroplanes not moving at very high speeds, this effect is not likely to be a serious drawback.

The simplest of such centre lines to design are those in which  $g_i$  is constant in each of the two segments

$0 \leq x \leq X$ ,  $X \leq x \leq 1$ , with a discontinuity at  $x = X$  (Fig. 11). Moreover, these are the designs which, for various reasons, are most likely to be employed in such cases as we are considering, where it is required to reduce  $-C_{M_0}$  for a suction aerofoil

to be used at speeds where compressibility effects will not be important. Experimental information should, however, be obtained for aerofoils with such centre lines as soon as convenient.

FIG 11.



With the graph of  $g_i$  as in Fig. 11,

$$g_i = k \quad (0 < x < X),$$

$$= -k' \quad (X < x < 1);$$

$$G_i = kx \quad (0 < x < X)$$

$$= (k + k')X - k'x \quad (X < x < 1);$$

$$A_1 = \frac{4}{\pi} \left\{ kX - k'(1 - X) \right\};$$



$$A_0 = -\frac{k+k'}{\pi} \left\{ X \ln X + (1-X) \ln (1-X) \right\};$$

$$y_0 = \frac{k+k'}{\pi} \left\{ (x-X) \ln |x-X| - [(1-X) \ln (1-X)] x + [X \ln X](1-x) \right\}$$

$$-\frac{k}{\pi} x \ln x + \frac{k'}{\pi} (1-x) \ln (1-x);$$

$$\frac{dy_c}{dx} - A_0 = \frac{k+k'}{\pi} \ln |x-X| - \frac{k}{\pi} \ln x - \frac{k'}{\pi} \ln (1-x);$$

$$-C_{M_0} = k(2X^2 - X) - k'(1 + X - 2X^2);$$

$$\left( \frac{\pi}{a_0} + \frac{1}{2} \right) C_{Lopt} = \pi A_1 = 4kX - 4k'(1-X).$$

$\beta$ ,  $\varepsilon_c(0)$ ,  $\alpha_{opt}$ ,  $\varepsilon_c(\theta)$ ,  $\varepsilon'_c(\theta)$  are, as usual, to be found from eqns. (6), (9), (27) and (28).

When the value of  $X$  has been selected, appropriate values of  $k$  and  $k'$  may be found for the desired values of  $C_{Lopt}$  and  $-C_{M_0}$ . For example, with  $X = 0.75$ , if the desired values of  $C_{Lopt}$  and  $-C_{M_0}$  are  $0.2$  and  $0.015$ , respectively, we have, assuming  $a_0 = 2\pi$ ,

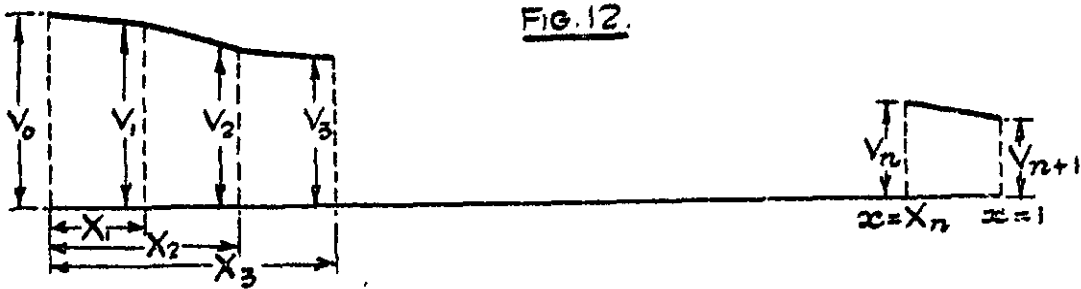
$$3k - k' = 0.2, \quad 0.375k - 0.625k' = 0.015,$$

whence  $k = 0.075$ ,  $k' = 0.02$ .

### 13. The Graph of $g_i$ Composed of Straight Lines. Basic Solutions

If the graph of  $g_i$  is composed of straight lines, then  $g_i$  may be expressed as the sum of a number of certain 'basic' values, and all those quantities which depend linearly on  $g_i$  ( $G_i$ ,  $A_1$ ,  $A_0$ ,  $C_{Lopt}$  and  $\alpha_{opt}$  (for a given  $a_0$ ),  $\beta$ ,  $C_{M_0}$ ,  $y_c$ ,  $\psi_c$ ,  $dy_c/dx$ ,  $\varepsilon_c(\theta)$ ,  $\varepsilon'_c(\theta)$ ) may be found as the sum of the corresponding values for the 'basic'  $g_i$ . Once the values for the 'basic'  $g_i$  are all tabulated, we have a convenient numerical process for finding these values in other cases.

Let the values of  $g_i$  be given at  $x = 0, X_1, X_2, \dots, X_n, 1$ , ( $0 < X_1 < X_2 \dots < X_n < 1$ ) and let the graph of  $g_i$  against  $x$  between any two of these values of  $x$  which are consecutive be a straight line. We first assume that  $g_i$  is continuous; we shall remove this restriction later. Let the values of  $g_i$  at the specified values of  $x$  be  $V_0, V_1, V_2, \dots, V_n, V_{n+1}$ , respectively (Fig. 12).



The simplest case is that in which  $V_0 = V_1$  and  $V_{n+1} = 0$ . The 'basic' values of  $g_i$  are then those of §10, Fig. 8, with  $X = X_1, X_2, \dots, X_n$  in turn. Denote the value of  $g_i$  whose graph is shown in Fig. 8 by  $g_i(k; X)$ . Then if  $V_0 = V_1$  and  $V_{n+1} = 0$ , the value of  $g_i$  whose graph is shown in Fig. 12 is given by

$$g_i = \sum_{r=1}^n g_i(a_r; X_r) \quad \dots(59)$$

if we make the values of the two sides of this equation agree at  $x = X_r (r = 1, 2, \dots, n)$ , since they then necessarily agree at  $x = 0$ , are both zero at  $x = 1$ , and both vary linearly with  $x$  between 0 and  $X_1, X_1$  and  $X_2$ , and so on. We have therefore exactly  $n$  linear equations from which to determine the  $n$  unknowns  $a_r$ . The simplest method of solution is to equate the changes of slope at  $x = X_1, x = X_2$  and so on. Proceeding in this way we find that

$$\left. \begin{aligned} a_1 &= (V_1 - V_2) \frac{1 - X_1}{X_2 - X_1}, \\ a_r &= (V_r - V_{r+1}) \frac{1 - X_r}{X_{r+1} - X_r} - (V_{r-1} - V_r) \frac{1 - X_r}{X_r - X_{r-1}} \\ &\quad (r = 2, 3, \dots, n-1; n > 2), \\ a_n &= V_n - (V_{n-1} - V_n) \frac{1 - X_n}{X_n - X_{n-1}} = V_n \frac{1 - X_{n-1}}{X_n - X_{n-1}} - V_{n-1} \frac{1 - X_n}{X_n - X_{n-1}} \end{aligned} \right\} \dots(6a)$$

and/

and we may easily verify algebraically that with these values the sum on the right in eqn. (59) has the values  $V_1$  at  $x = 0$  and  $x = X_1$ ,  $V_2$  at  $x = X_2$ , and so on.

The values of  $\beta$ ,  $C_{M_0}$ ,  $y_c$ ,  $\psi_c$ ,  $\varepsilon_c$ ,  $\varepsilon'_c$  for all such cases may therefore be found from Tables I, II and III. In those tables values are given for  $\left(\frac{\pi}{a_0} + \frac{1}{2}\right) C_{Lopt} = 1$ . Since the value of  $\left(\frac{\pi}{a_0} + \frac{1}{2}\right) C_{Lopt}$  corresponding to  $a_r$  is  $2a_r(1 + X_r)$ , the values in these tables must be multiplied by  $2a_r(1 + X_r)$ , where the  $a_r$  have the value found above, and then added together.

The simplest composite case occurs when  $n = 2$ . (Fig. 9 and Ref. 12). If, following the notation of Ref. 12, we put  $V_1 = k$ ,  $V_2 = ks$ , then

$$a_1 = k(1 - s) \frac{1 - X_1}{X_2 - X_1}, \quad a_2 = k \frac{s(1 - X_1) - (1 - X_2)}{X_2 - X_1}.$$

If  $V_{n+1} \neq 0$ , we must introduce, as another 'basic'  $g_i$ , the constant  $V_{n+1}$ , which we may also denote by  $g_i(V_{n+1}; 1)$

[Fig. 7 with  $k = V_{n+1}$ ]. Then

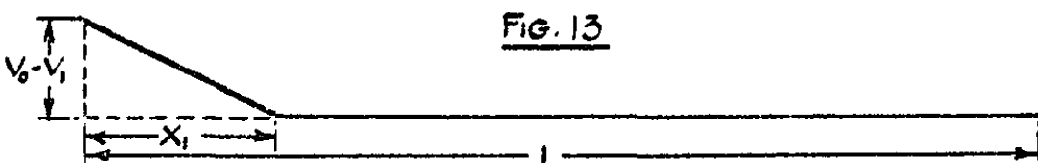
$$g_i = \sum_{r=1}^n g_i(a_r; X_r) + V_{n+1},$$

where the values of  $a_r$  are given by the same formulae (60) as before with  $V_r - V_{n+1}$  in place of  $V_r$ , i.e.  $a_r$  is given by exactly the same formula for  $r = 1, 2, \dots, n-1$  and

$$a_n = V_n - V_{n+1} - (V_{n-1} - V_n) \frac{1 - X_n}{X_n - X_{n-1}}.$$

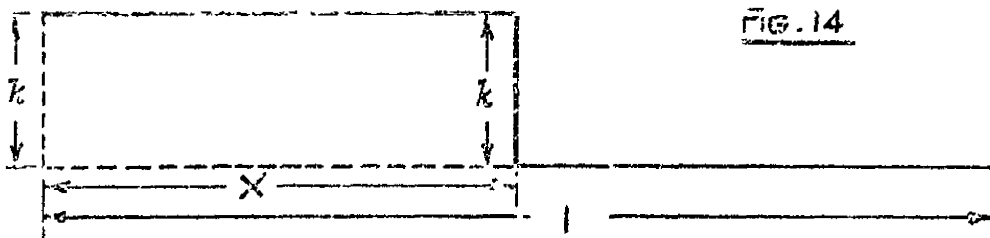
The formulae for  $g_i$  constant are contained in §9, and numerical values are shown in Tables I, II, and III under  $X = 1$  for  $C_{Lopt} \left(\frac{\pi}{a_0} + \frac{1}{2}\right) = 1$ ; these values must be multiplied by  $4V_{n+1}$  and added to the others.

Finally if  $V_0 \neq V_1$ , we add to the sum on the right in (59) another 'basic'  $g_i$ , shown in Fig. 13, for which  $g_i = 0$  for  $x \geq X_1$ ,  $g_i(0) = V_0 - V_1$ , and  $g_i$  varies linearly with  $x$  for  $0 \leq x < X_1$ .



The formulae for this 'basic'  $g_i$  are contained in the second section of Appendix III if we put  $b = c = d = 0$ ,  $a = V_0 - V_1$  (see Fig. 5). No tables have been prepared since it is not clear what useful purpose would be served by designing centre lines with  $V_0 \neq V_1$ .

We turn next to the case in which  $g_i$  has one or more discontinuities. The additional 'basic'  $g_i$  required may be taken as that in Fig. 14, and denoted by  $g_i(k; X; c)$ ; it is



equal to  $k$  for  $0 < x < X$ , and to  $0$  for  $X < x < 1$ . Let us suppose first that  $g_i$  has only one discontinuity, at  $x = X_s$ , and that as  $x \rightarrow X_s - 0$ ,  $g_i \rightarrow V_s$ , but that as  $x \rightarrow X_s + 0$ ,  $g_i \rightarrow W_s$ . It will be sufficient to write out the formulae with  $V_0 = V_1$ ; then

$$g_1 = g_i(V_s - W_s; X_s; 0) + \sum_{r=1}^n g_i(a_r; X_r) + V_{n+1},$$

and the values of  $a_r$  are the same as before, with  $V_r - (V_s - W_s)$  substituted for  $V_r$  for  $r = 1, 2, 3, \dots, s$ . Hence the  $a_r$  are given by the same expression as before, namely

$$a_1 = (V_1 - V_2) \frac{1 - X_1}{X_2 - X_1};$$

$$a_r = (V_r - V_{r+1}) \frac{1 - X_r}{X_{r+1} - X_r} - (V_{r-1} - V_r) \frac{1 - X_r}{X_r - X_{r-1}} \quad (r > 1, n > 2)$$

for  $r < s-1$  and for  $s+2 < r < n-1$ , while

$a_s/$

$$a_s = (W_s - V_{s+1}) \frac{1 - X_s}{X_{s+1} - X_s} - (V_{s-1} - V_s) \frac{1 - X_s}{X_s - X_{s-1}},$$

$$a_{s+1} = (V_{s+1} - V_{s+2}) \frac{1 - X_{s+1}}{X_{s+2} - X_{s+1}} - (W_s - V_{s+1}) \frac{1 - X_s}{X_{s+1} - X_s},$$

and

$$a_n = V_n - (V_{n-1} - V_n) \frac{1 - X_n}{X_n - X_{n-1}}$$

as before, if  $s < n-1$ .

If there are two discontinuities, one at  $x = X_s$  and one at  $x = X_t$ , the discontinuity at  $X_s$  being as before and that at  $X_t$  being given by a change in  $g_i$  from  $V_t$  to  $W_t$ , then

$$g_i - g_i(V_s - W_s; X_s; 0) - g_i(V_t - W_t; X_t; 0) - V_{n+1}$$

is continuous, has zero slope for  $0 < x < X_1$ , and is zero at  $x = 1$ ; hence it can be expressed as

$$\sum_{r=1}^n g_i(a_r; X_r).$$

The values of the expression at  $x = X_r$  are

$$V_r - (V_s - W_s) - (V_t - W_t) - V_{n+1} \quad (r < s),$$

$$V_r - (V_t - W_t) - V_{n+1} \quad (s < r < t),$$

$$V_r - V_{n+1} \quad (t < r < n);$$

and the  $a_r$  are given by the same expressions (60) as before, if these values be substituted for  $V_r$ .

In the simplest composite case,  $n = 2$ , (Fig. 1),  $V_0 = a$ ,  
 $V_1 = b$ ,  $W_1 = c$ ,  $V_2 = d$ ,  $W_2 = e$ ,  $V_3 = f$ ,  
 $g_i = g_i(a_1; X_1) + g_i(a_2; X_2) + g_i(a-b; 0; X_1; 0) + g_i(b-c; X_1; 0)$   
 $+ g_i(d-e; X_2; 0) + f,$

where the third term on the right denotes the function whose graph is shown in Fig. 13, and

$a_1/$

$$a_1 = (c - d) \frac{1 - X_1}{X_2 - X_1}, \quad a_2 = e - f - (c - d) \frac{1 - X_2}{X_2 - X_1}.$$

The solution when  $g_1$  has the form depicted in Fig. 14 is contained in §12, by putting  $k' = 0$  in the formulae there given. (See Fig. 11). Systematic tabulation for various values of  $X$  has not yet been undertaken, but it is recommended that such tables be prepared as soon as suction aerofoils are likely to come into general use.

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Addendum to above - A.R.C. 8139.
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Table 1/

Table 1

Centre Lines with  $g_1$  Constant for  $0 \leq x \leq X$ , and Decreasing Linearly to Zero for  $X \leq x \leq 1$

$$\text{Values for } \left( \frac{\pi}{a_0} + \frac{1}{2} \right) C_{\text{Lopt}} = 1$$

Some Constants

$X_1$	k	$K_0$	$K_1$	$K_2$	$K_3$	$A_0$	$\beta$	$-C_{M_0}$	$-\varepsilon_c(0)$
0.25	0.4000 0000	0.1954 4949	0.2931 7424	0.0063 8129	0.0073 5452	0.0700 4326 <sub>5</sub>	0.0891 1	0.1	0.2292 0
0.3	0.3846 1538 <sub>5</sub>	0.2013 5593	0.2818 9831	0.0058 0768	0.0094 7563	0.0670 2112	0.0921 3	0.1064 1	0.2261 8
0.35	0.3703 7037	0.2088 1356	0.2714 5763	0.0048 4290	0.0116 6258 <sub>5</sub>	0.0637 8917	0.0953 7	0.1135 8	0.2229 4
0.4	0.3571 4286	0.2181 3559 <sub>5</sub>	0.2617 6271	0.0035 3274	0.0138 6878	0.0603 7379	0.0987 8	0.1214 3	0.2195 3
0.45	0.3448 2759	0.2297 6038	0.2527 3641	+0.0019 1065	0.0161 3480	0.0567 9166	0.1023 6	0.1298 9	0.2159 5
0.5	0.3333 3333	0.2443 1187	0.2443 1187	0	0.0183 8630	0.0530 5165	0.1061 0	0.1388 9	0.2122 1
0.55	0.3225 8064 <sub>5</sub>	0.2627 0093	0.2364 3084	-0.0021 8457	0.0206 3261	0.0491 5573	0.1100 0	0.1483 9	0.2083 1
0.6	0.3125 0000	0.2863 0297	0.2290 4237 <sub>5</sub>	-0.0046 3672	0.0228 6574	0.0450 9920	0.1140 6	0.1583 3	0.2042 5
0.65	0.3030 3030	0.3172 8814	0.2221 0170	-0.0073 5869	0.0250 7976	0.0408 7008 <sub>5</sub>	0.1182 8	0.1686 9	0.2000 2 <sub>5</sub>
0.7	0.2941 1765	0.3592 8216	0.2155 6929	-0.0103 6273	0.0272 7022	0.0364 4755	0.1227 1	0.1794 1	0.1956 0 <sub>5</sub>
0.75	0.2857 1429	0.4188 2034	0.2094 1017	-0.0136 7419	0.0294 3387	0.0317 9865	0.1273 6	0.1904 8	0.1909 5
0.8	0.2777 7778	0.5089 8305 <sub>5</sub>	0.2035 9322	-0.0173 3780	0.0315 6835 <sub>5</sub>	0.0268 7191	0.1322 8	0.2018 5	0.1860 3
0.85	0.2702 7027	0.6603 0234	0.1980 9070	-0.0214 3135	0.0336 7200	0.0215 8350	0.1375 7	0.2135 1	0.1807 4
0.9	0.2631 5789 <sub>5</sub>	0.9643 8895	0.1928 7779	-0.0260 9981	0.0357 4369 <sub>5</sub>	0.0157 8307	0.1433 7	0.2254 4	0.1749 4
0.95	0.2564 1026	1.8793 2205	0.1879 3220 <sub>5</sub>	-0.0316 7009	0.0377 8273 <sub>5</sub>	0.0091 3887	0.1500 2	0.2376 1	0.1682 9
1	0.25	← See B9 →				0	0.1591 5	0.25	0.1591 5

- 31 -

Table 2//



Table 2

Centre Lines with  $g_i$  Constant for  $0 \leq x \leq X$ , and Decreasing Linearly to Zero for  $X \leq x \leq 1$ 

$$\text{Values for } \left( \frac{\pi}{a_0} + \frac{1}{2} \right) C_{\text{lopt}} = 1$$

Centre Line Ordinates

$x \backslash X$	0.3	0.35	0.4	0.45	0.5	0.55	0.6	0.65	0.7	0.75	0.8	0.85	0.9	0.95	1.0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0.001	0.000976	0.000945	0.000915	0.000887	0.000859	0.000833	0.000808	0.000734	0.000761	0.000738	0.000717	0.000695	0.000674	0.000652	0.000629
0.002	0.001782	0.001726	0.001672	0.001621	0.001572	0.001524	0.001479	0.001435	0.001392	0.001351	0.001310	0.001271	0.001231	0.001192	0.001148
0.003	0.002523	0.002445	0.002370	0.002298	0.002228	0.002161	0.002097	0.002035	0.001974	0.001915	0.001858	0.001801	0.001745	0.001688	0.001625
0.004	0.003223	0.003124	0.003029	0.002937	0.002849	0.002763	0.002718	0.002602	0.002524	0.002449	0.002375	0.002303	0.002230	0.002157	0.002075
0.005	0.003892	0.003773	0.003659	0.003548	0.003442	0.003339	0.003240	0.003144	0.003051	0.002959	0.002870	0.002782	0.002694	0.002605	0.002505
0.006	0.004535	0.004398	0.004265	0.004137	0.004014	0.003895	0.003779	0.003667	0.003558	0.003452	0.003347	0.003244	0.003141	0.003036	0.002919
0.007	0.005158	0.005003	0.004853	0.004708	0.004568	0.004432	0.004301	0.004174	0.004050	0.003928	0.003809	0.003691	0.003574	0.003454	0.003319
0.0075	0.005463	0.005299	0.005140	0.004987	0.004839	0.004696	0.004557	0.004422	0.004290	0.004162	0.004035	0.003910	0.003786	0.003658	0.003515
0.008	0.005764	0.005591	0.005424	0.005263	0.005106	0.004955	0.004809	0.004666	0.004528	0.004392	0.004259	0.004127	0.003994	0.003859	0.003708
0.009	0.006353	0.006164	0.005981	0.005803	0.005632	0.005465	0.005304	0.005147	0.004994	0.004844	0.004697	0.004551	0.004405	0.004255	0.004087
0.010	0.006929	0.006724	0.006525	0.006332	0.006145	0.005964	0.005788	0.005616	0.005449	0.005286	0.005125	0.004965	0.004805	0.004641	0.004456
0.012	0.008045	0.007830	0.007579	0.007356	0.007140	0.006930	0.006726	0.006527	0.006333	0.006143	0.005955	0.005769	0.005582	0.005390	0.005173
0.0125	0.008317	0.008073	0.007836	0.007606	0.007383	0.007166	0.006955	0.006750	0.006549	0.006352	0.006158	0.005965	0.005772	0.005573	0.005347
0.014	0.009118	0.008853	0.008594	0.008343	0.008099	0.007861	0.007631	0.007405	0.007185	0.006969	0.006755	0.006543	0.006330	0.006111	0.005862
0.016	0.010156	0.009862	0.009576	0.009298	0.009027	0.008763	0.008506	0.008255	0.008010	0.007768	0.007530	0.007293	0.007054	0.006808	0.006528
0.018	0.011162	0.010842	0.010529	0.010224	0.009927	0.009638	0.009356	0.009080	0.008810	0.008545	0.008282	0.008020	0.007757	0.007485	0.007174
0.020	0.012140	0.011794	0.011456	0.011126	0.010804	0.010490	0.010183	0.009884	0.009590	0.009300	0.009014	0.008728	0.008440	0.008143	0.007802
0.025	0.014478	0.014073	0.013674	0.013285	0.012903	0.012531	0.012166	0.011809	0.011458	0.011111	0.010768	0.010425	0.010078	0.009718	0.009303
0.030	0.016688	0.016226	0.015774	0.015329	0.014892	0.014465	0.014046	0.013634	0.013229	0.012828	0.012430	0.012032	0.011628	0.011208	0.010722
0.035	0.018790	0.018279	0.017774	0.017277	0.016789	0.016309	0.015839	0.015375	0.014918	0.014466	0.014016	0.013565	0.013105	0.012629	0.012107
0.04	0.020798	0.020240	0.019688	0.019142	0.018605	0.018077	0.017557	0.017044	0.016538	0.016036	0.015536	0.015034	0.014522	0.013988	0.013365
0.05	0.024575	0.023935	0.023296	0.022661	0.022034	0.021415	0.020803	0.020198	0.019599	0.019003	0.018408	0.017808	0.017195	0.016553	0.015797
0.06	0.028083	0.027371	0.026656	0.025942	0.025234	0.024531	0.023836	0.023146	0.022460	0.021776	0.021091	0.020399	0.019691	0.018944	0.018062
0.07	0.031362	0.030589	0.029806	0.029022	0.028240	0.027461	0.026688	0.025918	0.025152	0.024386	0.023616	0.022837	0.022036	0.021190	0.020184
0.075	0.032925	0.032124	0.031312	0.030495	0.029678	0.028864	0.028054	0.027247	0.026442	0.025636	0.024826	0.024004	0.023159	0.022265	0.021198
0.08	0.034441	0.033615	0.032774	0.031926	0.031077	0.030229	0.029383	0.028540	0.027698	0.026854	0.026004	0.025141	0.024252	0.023311	0.022184
0.09	0.037341	0.036472	0.035580	0.034675	0.033765	0.032852	0.031940	0.031027	0.030114	0.029196	0.028269	0.027327	0.026353	0.025319	0.024075
0.10	0.040080	0.039175	0.038238	0.037283	0.036317	0.035346	0.034371	0.033394	0.032413	0.031425	0.030426	0.029406	0.028351	0.027228	0.025869
0.12	0.045120	0.044166	0.043161	0.042122	0.041061	0.039986	0.038900	0.037805	0.036701	0.035583	0.034447	0.033284	0.032074	0.030779	0.029199

Table Continued/

Table 2 Continued

X x	0.3	0.35	0.4	0.45	0.5	0.55	0.6	0.65	0.7	0.75	0.8	0.85	0.9	0.95	1.0
0.14	0.049640	0.048666	0.047616	0.046515	0.045379	0.044217	0.043036	0.041838	0.040623	0.039388	0.038127	0.036830	0.035476	0.034018	0.032226
0.15	0.051721	0.050748	0.049685	0.048560	0.047393	0.046195	0.044971	0.043726	0.042461	0.041171	0.039852	0.038492	0.037069	0.035534	0.033538
0.16	0.053690	0.052725	0.051654	0.050512	0.049318	0.048086	0.046824	0.045536	0.044223	0.042882	0.041507	0.040086	0.038596	0.036985	0.034988
0.18	0.057309	0.056381	0.055313	0.054149	0.052915	0.051628	0.050299	0.048933	0.047533	0.046096	0.044617	0.043081	0.041464	0.039707	0.037512
0.20	0.060520	0.059659	0.058619	0.057453	0.056195	0.054868	0.053485	0.052054	0.050578	0.049055	0.047480	0.045838	0.044102	0.042206	0.039821
0.22	0.063340	0.062581	0.061592	0.060444	0.059180	0.057828	0.056404	0.054918	0.053377	0.051778	0.050116	0.048375	0.046527	0.044499	0.041930
0.24	0.065778	0.065157	0.064246	0.063137	0.061884	0.060521	0.059069	0.057541	0.055944	0.054278	0.052538	0.050707	0.048753	0.046600	0.043854
0.25	0.066853	0.066319	0.065458	0.064376	0.063136	0.061773	0.060311	0.058766	0.057145	0.055449	0.053672	0.051799	0.049796	0.047583	0.044749
0.26	0.067833	0.067396	0.066593	0.065545	0.064321	0.062962	0.061494	0.059935	0.058293	0.056569	0.054758	0.052844	0.050793	0.048521	0.045602
0.28	0.069494	0.069301	0.068638	0.067675	0.066498	0.065159	0.063689	0.062110	0.060432	0.058660	0.056787	0.054797	0.052655	0.050271	0.047186
0.30	0.070721	0.070867	0.070385	0.069533	0.068423	0.067119	0.065661	0.064074	0.062371	0.060558	0.058631	0.056574	0.054347	0.051856	0.048611
0.32	0.071431	0.072084	0.071833	0.071121	0.070100	0.068848	0.067416	0.065832	0.064115	0.062271	0.060299	0.058180	0.055875	0.053285	0.049885
0.34	0.071733	0.072924	0.072975	0.072440	0.071531	0.070350	0.068958	0.067390	0.065669	0.063804	0.061794	0.059622	0.057246	0.054561	0.051012
0.35	0.071754	0.073181	0.073429	0.072998	0.072155	0.071017	0.069650	0.068095	0.066376	0.064504	0.062478	0.060282	0.057873	0.055144	0.051522
0.36	0.071694	0.073302	0.073802	0.073487	0.072717	0.071627	0.070290	0.068751	0.067037	0.065160	0.063121	0.060903	0.058463	0.055690	0.051997
0.38	0.071352	0.073228	0.074290	0.074254	0.073655	0.072679	0.071414	0.069917	0.068222	0.066343	0.064283	0.062027	0.059530	0.056675	0.052845
0.40	0.070758	0.072807	0.074390	0.074731	0.074344	0.073504	0.072330	0.070891	0.069225	0.067355	0.065283	0.062997	0.060449	0.057520	0.053557
0.42	0.069876	0.072087	0.074004	0.074899	0.074773	0.074099	0.073037	0.071671	0.070049	0.068197	0.066124	0.063815	0.061224	0.058225	0.054136
0.44	0.068786	0.071101	0.073247	0.074723	0.074932	0.074461	0.073533	0.072257	0.070692	0.068871	0.066805	0.064482	0.061855	0.058794	0.054585
0.45	0.068162	0.070516	0.072751	0.074481	0.074906	0.074551	0.073701	0.072477	0.070946	0.069145	0.067086	0.064759	0.062118	0.059028	0.054760
0.46	0.067489	0.069874	0.072184	0.074104	0.074805	0.074580	0.073814	0.072648	0.071155	0.069376	0.067328	0.064999	0.062345	0.059228	0.054904
0.48	0.065999	0.068430	0.070855	0.073051	0.074362	0.074446	0.073874	0.072839	0.071435	0.069712	0.067691	0.065367	0.062693	0.059528	0.055095
0.50	0.064333	0.066786	0.069289	0.071675	0.073545	0.074042	0.073705	0.072826	0.071529	0.069876	0.067896	0.065586	0.062899	0.059693	0.055159
0.52	0.062505	0.064961	0.067510	0.070026	0.072243	0.073346	0.073296	0.072604	0.071434	0.069866	0.067939	0.065653	0.062964	0.059724	0.055095
0.54	0.060529	0.062970	0.065539	0.068138	0.070579	0.072313	0.072632	0.072163	0.071144	0.069680	0.067819	0.065568	0.062886	0.059621	0.054904
0.55	0.059488	0.061916	0.064486	0.067114	0.069636	0.071642	0.072197	0.071857	0.070924	0.069519	0.067696	0.065468	0.062793	0.059518	0.054760
0.56	0.058416	0.060827	0.063392	0.066039	0.068627	0.070831	0.071690	0.071492	0.070653	0.069312	0.067532	0.065329	0.062664	0.059382	0.054585
0.58	0.056178	0.058546	0.061088	0.063750	0.066430	0.068905	0.070437	0.070578	0.069952	0.068756	0.067075	0.064933	0.062295	0.059005	0.054136
0.60	0.053828	0.056140	0.058641	0.061292	0.064019	0.066665	0.068300	0.069398	0.069030	0.068006	0.066442	0.064376	0.061777	0.058490	0.053557
0.62	0.051376	0.053621	0.056066	0.058683	0.061419	0.064165	0.066651	0.067924	0.067872	0.067053	0.065628	0.063654	0.061108	0.057833	0.052845
0.64	0.048834	0.051001	0.053376	0.055938	0.058652	0.061443	0.064133	0.066102	0.066458	0.065884	0.064625	0.062761	0.060281	0.057031	0.051997
0.65	0.047531	0.049657	0.051992	0.054520	0.057212	0.060009	0.062761	0.065027	0.065647	0.065215	0.064049	0.062248	0.059808	0.056575	0.051522

Table Continued/

Table 2 Continued

x \ X	0.3	0.35	0.4	0.45	0.5	0.55	0.6	0.65	0.7	0.75	0.8	0.85	0.9	0.95	1.0
0.66	0.046210	0.048292	0.050584	0.053073	0.055739	0.058531	0.061332	0.063797	0.064761	0.064486	0.063422	0.061690	0.059294	0.056081	0.051012
0.68	0.043516	0.045505	0.047703	0.050104	0.052697	0.055453	0.058297	0.061015	0.062737	0.062839	0.062009	0.060434	0.058138	0.054977	0.049085
0.70	0.040763	0.042651	0.044745	0.047044	0.049544	0.052232	0.055066	0.057911	0.060298	0.060916	0.060370	0.058982	0.056808	0.053714	0.048611
0.72	0.037959	0.039741	0.041722	0.043906	0.046296	0.048890	0.051668	0.054553	0.057281	0.058678	0.058486	0.057321	0.055294	0.052285	0.047186
0.74	0.035116	0.036785	0.038646	0.040704	0.042968	0.045444	0.048130	0.050987	0.053867	0.056059	0.056330	0.055436	0.053585	0.050683	0.045602
0.75	0.033683	0.035294	0.037091	0.039083	0.041279	0.043689	0.046316	0.049139	0.052049	0.054560	0.055139	0.054404	0.052653	0.049813	0.044749
0.76	0.032244	0.033795	0.035528	0.037452	0.039576	0.041915	0.044477	0.047252	0.050167	0.052878	0.053866	0.053307	0.051668	0.048896	0.043854
0.78	0.029352	0.030782	0.032382	0.034162	0.036136	0.038319	0.040731	0.043380	0.046243	0.049149	0.051034	0.050907	0.049525	0.046914	0.041930
0.80	0.026453	0.027757	0.029219	0.030849	0.032661	0.034675	0.036914	0.039401	0.042145	0.045077	0.047713	0.048198	0.047137	0.044721	0.039821
0.82	0.023556	0.024732	0.026051	0.027525	0.029168	0.030999	0.033047	0.035342	0.037913	0.040756	0.043675	0.045125	0.044473	0.042300	0.037512
0.84	0.020674	0.021719	0.022893	0.024206	0.025671	0.027311	0.029152	0.031229	0.033584	0.036253	0.039186	0.041591	0.041495	0.039625	0.034988
0.85	0.019243	0.020221	0.021321	0.022552	0.023927	0.025468	0.027200	0.029161	0.031395	0.033950	0.036826	0.039580	0.039871	0.038183	0.033638
0.86	0.017819	0.018731	0.019757	0.020905	0.022189	0.023628	0.025249	0.027089	0.029194	0.031622	0.034406	0.037318	0.038146	0.036666	0.032226
0.88	0.015004	0.015782	0.016658	0.017639	0.018737	0.019970	0.021362	0.022949	0.024778	0.026913	0.029434	0.032341	0.034331	0.033379	0.029199
0.90	0.012244	0.012888	0.013613	0.014425	0.015335	0.016358	0.017515	0.018837	0.020369	0.022175	0.024349	0.026997	0.029841	0.029700	0.025869
0.92	0.009555	0.010065	0.010640	0.011283	0.012004	0.012815	0.013733	0.014784	0.016006	0.017456	0.019224	0.021453	0.024272	0.025525	0.022184
0.925	0.008896	0.009373	0.009910	0.010511	0.011185	0.011943	0.012801	0.013784	0.014927	0.016285	0.017946	0.020052	0.022779	0.024384	0.021198
0.94	0.006956	0.007334	0.007759	0.008235	0.008768	0.009367	0.010046	0.010823	0.011729	0.012807	0.014134	0.015842	0.018167	0.020651	0.018062
0.95	0.005698	0.006010	0.006362	0.006755	0.007195	0.007689	0.008249	0.008890	0.009637	0.010528	0.011626	0.013049	0.015031	0.017786	0.015797
0.96	0.004471	0.004719	0.004997	0.005309	0.005657	0.006047	0.006490	0.006996	0.007586	0.008289	0.009157	0.010287	0.011886	0.014406	0.013365
0.975	0.002702	0.002854	0.003025	0.003216	0.003429	0.003667	0.003937	0.004245	0.004604	0.005030	0.005557	0.006244	0.007227	0.008919	0.009303
0.98	0.002133	0.002254	0.002390	0.002541	0.002710	0.002900	0.003113	0.003357	0.003640	0.003977	0.004392	0.004934	0.005709	0.007063	0.007802
0.9875	0.001304	0.001379	0.001463	0.001556	0.001660	0.001776	0.001907	0.002057	0.002230	0.002435	0.002667	0.003016	0.003486	0.004313	0.005347
1.0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

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Table 3/

Table 3 Continued

x	$X_1 = 0.7$			$X_1 = 0.75$			$X_1 = 0.8$			$X_1 = 0.85$		
	$\Psi_c$	$\epsilon_c$	$\epsilon'_c$	$\Psi_c$	$\epsilon_c$	$\epsilon'_c$	$\Psi_c$	$\epsilon_c$	$\epsilon'_c$	$\Psi_c$	$\epsilon_c$	$\epsilon'_c$
0	0	-0.1956	*	0	-0.1909 <sub>5</sub>	*	0	-0.1860	*	0	-0.1807	*
0.005	0.04326	-0.1753	0.1402	0.04195	-0.1712 <sub>5</sub>	0.1360	0.04069	-0.1669	0.1320	0.03944	-0.1621	0.1283
0.0075	0.04972	-0.1708	0.1389	0.04824	-0.1669	0.1347	0.04677	-0.1627	0.1307	0.04532	-0.1580	0.1269
0.0125	0.05895	-0.1639	0.1369	0.05717	-0.1601 <sub>5</sub>	0.1326	0.05543	-0.1561	0.1286	0.05369	-0.1517	0.1248
0.025	0.07339	-0.1512	0.1336	0.07117	-0.1479	0.1293	0.06897	-0.1443	0.1252	0.06677	-0.1402	0.1213 <sub>5</sub>
0.05	0.08993	-0.1337	0.1297	0.08719	-0.1309	0.1253	0.08446	-0.1278	0.1211	0.08171	-0.1243	0.1171 <sub>5</sub>
0.075	0.1004	-0.1203	0.1273	0.0973	-0.1181	0.1228	0.0943	-0.1154	0.1185	0.0911	-0.1122 <sub>5</sub>	0.1144
0.10	0.1080	-0.1091	0.1257	0.1047 <sub>5</sub>	-0.1072 <sub>5</sub>	0.1211	0.1014	-0.1050	0.1167	0.0980	-0.1022	0.1125
0.15	0.1189	-0.0902	0.1239	0.1153	-0.0890	0.1190	0.1116	-0.0874	0.1143	0.1078	-0.0853	0.1099
0.20	0.1264	-0.0739	0.1232	0.1226	-0.0734	0.1180	0.1187	-0.0725	0.1130	0.1146	-0.0709	0.1083
0.25	0.1320	-0.0591	0.1234	0.1280 <sub>5</sub>	-0.0593	0.1178	0.1240	-0.0589	0.1125	0.1196	-0.0580	0.1075
0.30	0.1361	-0.0452	0.1243	0.1321 <sub>5</sub>	-0.0461	0.1183	0.1279	-0.0463	0.1126	0.1234 <sub>5</sub>	-0.0460	0.1073
0.35	0.1392	-0.0319	0.1258	0.1352	-0.0334	0.1194	0.1310	-0.0343	0.1133	0.1264	-0.0345	0.1075
0.40	0.1413	-0.0187	0.1281	0.1375	-0.0210	0.1211	0.1333	-0.0225	0.1145	0.1286	-0.0234	0.1082
0.45	0.1426	-0.0056	0.1311	0.1390	-0.0086	0.1234	0.1348	-0.0108 <sub>5</sub>	0.1162	0.1302	-0.0123 <sub>5</sub>	0.1094
0.50	0.1431	+0.0077	0.1350	0.1397 <sub>5</sub>	+0.0040	0.1266	0.1358	+0.0009	0.1186	0.1312	-0.0013	0.1111
0.55	0.1426	0.0214	0.1400	0.1397	0.0168	0.1306	0.1361	0.0129	0.1218	0.1316	+0.0099	0.1135
0.60	0.1409	0.0359	0.1464	0.1388	0.0303	0.1359	0.1356	0.0255	0.1260	0.1314	0.0216	0.1166
0.65	0.1376	0.0515	0.1549	0.1367	0.0447	0.1429	0.1343	0.0388	0.1316	0.1305	0.0338	0.1209
0.70	0.1316	0.0686	0.1663	0.1329	0.0604	0.1523	0.1317	0.0532	0.1391	0.1287	0.0470	0.1266
0.75	0.1202	0.0852	0.1316	0.1260	0.0782	0.1654	0.1273	0.0694	0.1496	0.1256	0.0616	0.1345
0.80	0.1054	0.0990	0.0987	0.1127	0.0955	0.1251	0.1193	0.0882	0.1651	0.1205	0.0784	0.1463
0.85	0.0879	0.1099	0.0677	0.0951	0.1095	0.0870	0.1031	0.1066	0.1163	0.1108 <sub>5</sub>	0.0989	0.1655
0.90	0.0679	0.1179	0.0386	0.0739	0.1198 <sub>5</sub>	0.0512	0.0812	0.1207	0.0704	0.0900	0.1191	0.1025
0.925	0.0567	0.1207	0.0250	0.0618	0.1236 <sub>5</sub>	0.0344	0.0681	0.1259	0.0486	0.0761	0.1268	0.0724
0.95	0.04422	0.1226	0.0123	0.04831	0.1263	0.0185	0.05334	0.1298	0.0279	0.05987	0.1328	0.0436 <sub>5</sub>
0.975	0.02949	0.1235	0.0013	0.03222	0.1278	+0.0044	0.03559	0.1322	0.0090	0.03999	0.1367	0.0168
0.9875	0.02007	0.1234	-0.0028	0.02192	0.1279	-0.0018	0.02400 <sub>5</sub>	0.1326	0.0010	0.02715	0.1376	0.0049
1.000	0	0.1227	0	0	0.1274	0	0	0.1323	0	0	0.1376	0

\*See eqn.(29) and the remarks following that equation.

Table 3 Continued

x	$X_1 = 0.9$			$X_1 = 0.95$			$X_1 = 1.0$		
	$\psi_c$	$\varepsilon_c$	$\varepsilon'_c$	$\psi_c$	$\varepsilon_c$	$\varepsilon'_c$	$\psi_c$	$\varepsilon_c$	$\varepsilon'_c$
0	0	-0.1749	*	0	-0.1683	*	0	-0.15915	*
0.005	0.03819 <sub>5</sub>	-0.1568	0.1247	0.0369 <sub>5</sub>	-0.1506 <sub>5</sub>	0.1213	0.03551 <sub>5</sub>	-0.1420	0.1181
0.0075	0.04388	-0.1529	0.1233	0.04240	-0.1468	0.1199	0.04074	-0.1382	0.1167
0.0125	0.05195	-0.1467	0.1212	0.05016	-0.1408	0.1178	0.04813	-0.1324	0.1146
0.025	0.06455	-0.1355	0.1177	0.06224 <sub>5</sub>	-0.1299	0.1142	0.05959	-0.1218	0.1109 <sub>5</sub>
0.05	0.07890	-0.1201	0.1134	0.07595	-0.1150	0.1098 <sub>5</sub>	0.07248	-0.1073	0.1065
0.075	0.0879	-0.1085	0.1106	0.0845	-0.1037 <sub>5</sub>	0.1069	0.0805	-0.0964	0.1035
0.10	0.0945	-0.0988	0.1085	0.0908	-0.0944	0.1048	0.0862	-0.0874	0.1012
0.15	0.1038	-0.0825	0.1057	0.0995	-0.0787	0.1017	0.0942	-0.0722	0.0979 <sub>5</sub>
0.20	0.1103	-0.0687	0.1039	0.1055	-0.0654	0.0997	0.0995 <sub>5</sub>	-0.0595	0.0957
0.25	0.1150	-0.0563	0.1028	0.1099	-0.0535 <sub>5</sub>	0.0983	0.1033 <sub>5</sub>	-0.0481	0.0940
0.30	0.1186	-0.0448	0.1022	0.1132	-0.0426	0.0974	0.1061	-0.0376 <sub>5</sub>	0.0928
0.35	0.1213	-0.0339	0.1020	0.1156	-0.0322	0.0968	0.1080	-0.0278	0.0919
0.40	0.1234	-0.0234	0.1023	0.1174	-0.0222	0.0966	0.1093	-0.0183	0.0913
0.45	0.1249	-0.0130	0.1029	0.1186 <sub>5</sub>	-0.0124	0.0968	0.1101	-0.0091	0.0910
0.50	0.1258	-0.0026	0.1040	0.1194	-0.0027	0.0972 <sub>5</sub>	0.1103	0	0.0908
0.55	0.1262	+0.0079	0.1056	0.1196	+0.0070 <sub>5</sub>	0.0981	0.1101	+0.0091	0.0910
0.60	0.1261	0.0187	0.1078	0.1194	0.0170	0.0993	0.1093	0.0183	0.0913
0.65	0.1254	0.0299	0.1107	0.1186	0.0274	0.1011	0.1080	0.0278	0.0919
0.70	0.1240	0.0420	0.1147	0.1172	0.0383	0.1035	0.1061	0.0376 <sub>5</sub>	0.0928
0.75	0.1216	0.0551	0.1203	0.1150	0.0501	0.1068	0.1033 <sub>5</sub>	0.0481	0.0940
0.80	0.1178	0.0700	0.1286	0.1118	0.0632	0.1117	0.0995 <sub>5</sub>	0.0595	0.0957
0.85	0.1117	0.0878	0.1418	0.1069	0.0784	0.1193	0.0942	0.0722	0.0979 <sub>5</sub>
0.90	0.0995	0.1111	0.1670	0.0990	0.0974 <sub>5</sub>	0.1133	0.0862	0.0874	0.1012
0.925	0.0865	0.1237	0.1204	0.0926	0.1098	0.1462	0.0805	0.0964	0.1035
0.95	0.06897	0.1338	0.0753	0.08161	0.1261	0.1706	0.07248	0.1073	0.1065
0.975	0.04629	0.1408	0.0325	0.05713	0.1425	0.0797	0.05959	0.1218	0.1109 <sub>5</sub>
0.9875	0.03138	0.1429	0.0127	0.03882	0.1477 <sub>5</sub>	0.0362 <sub>5</sub>	0.04813	0.1324	0.1146
1.000	0	0.1434	0	0	0.1500	0	0	0.1591 <sub>5</sub>	0

\*See eqn.(29) and the remarks following that equation.

Appendix I

The Relation of the Velocities at the Leading and Trailing Edges to  $a_0$  and  $C_{Lopt}$

From Part II, eqn. (67), the velocity at the leading edge is given by

$$\frac{q}{U} = \frac{e^{C_0} [1 + \varepsilon'(0)]}{\psi_L} \left\{ \left( 1 - \frac{C_L^2}{a_0^2} \right)^{\frac{1}{2}} [\varepsilon(0) - \beta] + C_L \left[ \frac{1}{a_0} + \frac{e^{-C_0}}{2\pi} \right] \right\},$$

and at the trailing edge by

$$\frac{q}{U} = - \frac{e^{C_0} [1 + \varepsilon'(\pi)]}{\psi_T} \left[ \frac{1}{a_0} - \frac{e^{-C_0}}{2\pi} \right] C_L.$$

$C_L$  is known.  $\psi_L$ ,  $\psi_T$  are equal to  $(2\rho_L)^{\frac{1}{2}}$ ,  $(2\rho_T)^{\frac{1}{2}}$ , respectively, where  $\rho_L$  and  $\rho_T$  are the radii of curvature at the leading and trailing edges; hence  $\psi_L$  and  $\psi_T$  are given in terms of  $g_s$  by eqns. (13) and (14) of Part III;  $C_0$  is given in terms of  $g_s$  by eqns. (18) and (29) of Part III;  $\varepsilon'_c(0) = \varepsilon'_c(\pi) = 0$ , so from eqn. (33) of Part III

$$\varepsilon'(0) = \frac{1}{2}g_s(0) - \frac{1}{2}C_0, \quad \varepsilon'(\pi) = \frac{1}{2}g_s(\pi) - \frac{1}{2}C_0,$$

and  $\varepsilon'(0)$ ,  $\varepsilon'(\pi)$  are also given in terms of  $g_s$ .

Finally  $\varepsilon_s(0) = 0$ , so

$$\varepsilon(0) - \beta = \varepsilon_c(0) - \beta;$$

from Part II, eqn. (39),

$$\beta = \varepsilon_c(\pi) = \frac{1}{2}A_1 - A_0,$$

and similarly it may be shown that

$$\varepsilon_c(0) = -\frac{1}{2}A_1 - A_0,$$

so

$$\varepsilon(0) - \beta = -A_1 = - \left( \frac{1}{a_0} + \frac{1}{2\pi} \right) C_{Lopt}$$

(from eqn. 50, Part II). Hence the velocities at the leading and trailing edges may be expressed in terms of  $C_L$ ,  $g_s$ ,  $C_{Lopt}$  and  $a_0$ .

Appendix II

Lemma 1

$$\int_0^{\pi} \frac{1 - \cos t - \frac{2t}{\pi}}{\sin t} dt = 0.$$

This result is obvious, since the integrand is free from singularities at 0 and  $\pi$  and is antisymmetrical about  $\frac{1}{2}\pi$ .

Lemma 2

$$P \int_0^{\pi} \frac{1 - \cos t - \frac{2t}{\pi}}{\sin t(\cos \theta - \cos t)} dt = -\frac{1}{\sin^2 \theta} \left\{ (1 - \cos \theta) \ln \frac{1}{2}(1 - \cos \theta) + (1 + \cos \theta) \ln \frac{1}{2}(1 + \cos \theta) \right\}^*$$

To prove this result we note that

$$\begin{aligned} \int \frac{1 - \cos t}{\sin t(\cos \theta - \cos t)} dt &= \int \frac{\sin t}{(1 + \cos t)(\cos \theta - \cos t)} dt \\ &= \frac{1}{1 + \cos \theta} \ln \frac{|\cos \theta - \cos t|}{1 + \cos t}, \end{aligned}$$

and

$$\begin{aligned} \int \frac{dt}{\sin t(\cos \theta - \cos t)} &= \frac{1}{\sin^2 \theta} \ln |\cos \theta - \cos t| \\ &\quad - \frac{1}{2(1 + \cos \theta)} \ln (1 + \cos t) - \frac{1}{2(1 - \cos \theta)} \ln (1 - \cos t) \\ &= \frac{1}{\sin^2 \theta} \left\{ \ln |\cos \theta - \cos t| - \ln \sin t - \cos \theta \ln \tan \frac{1}{2}t \right\}, \end{aligned}$$

so

$$\begin{aligned} \int \frac{t dt}{\sin t(\cos \theta - \cos t)} &= \frac{t}{\sin^2 \theta} \ln |\cos \theta - \cos t| \\ &\quad - \frac{t}{2(1 + \cos \theta)} \ln (1 + \cos t) - \frac{t}{2(1 - \cos \theta)} \ln (1 - \cos t) \\ &\quad - \frac{1}{\sin^2 \theta} \int \left\{ \ln |\cos \theta - \cos t| - \ln \sin t - \cos \theta \ln \tan \frac{1}{2}t \right\} dt. \end{aligned}$$

Now/

\*  $\ln$  is used to denote  $\log_e$ .

Now

$$\int_0^{\pi} \ln \sin t \, dt = -\pi \ln 2,$$

$$\int_0^{\pi} \ln \tan \frac{1}{2}t \, dt = 0,$$

and

$$\begin{aligned} \int_0^{\pi} \ln |\cos \theta - \cos t| \, dt &= \frac{1}{2} \int_0^{2\pi} \left\{ \ln 2 + \ln \left| \sin \frac{1}{2}(\theta + t) \right| \right. \\ &\quad \left. + \ln \left| \sin \frac{1}{2}(t - \theta) \right| \right\} dt \\ &= \pi \ln 2 + \int_0^{2\pi} \ln \sin \frac{1}{2}t \, dt = \pi \ln 2 + 2 \int_0^{\pi} \ln \sin t \, dt \\ &= -\pi \ln 2, \end{aligned}$$

so

$$\int_0^{\pi} \left\{ \ln |\cos \theta - \cos t| - \ln \sin t - \cos \theta \ln \tan \frac{1}{2}t \right\} dt = 0.$$

Hence

$$\begin{aligned} P \int_0^{\pi} \frac{1 - \cos t - \frac{2t}{\pi}}{\sin t (\cos \theta - \cos t)} \, dt &= \left[ \frac{1}{\sin^2 \theta} \left( 1 - \cos \theta - \frac{2t}{\pi} \right) \ln |\cos \theta - \cos t| \right. \\ &\quad \left. - \frac{1}{1 + \cos \theta} \left( 1 - \frac{t}{\pi} \right) \ln (1 + \cos t) + \frac{t}{\pi(1 - \cos \theta)} \ln (1 - \cos t) \right]_0^{\pi} \\ &= -\frac{1}{1 - \cos \theta} \ln (1 + \cos \theta) + \frac{1}{1 - \cos \theta} \ln 2 \\ &\quad - \frac{1}{1 + \cos \theta} \ln (1 - \cos \theta) + \frac{1}{1 + \cos \theta} \ln 2 \\ &= -\frac{1}{\sin^2 \theta} \left\{ (1 - \cos \theta) \ln \frac{1 - \cos \theta}{2} + (1 + \cos \theta) \ln \frac{1 + \cos \theta}{2} \right\}. \end{aligned}$$



Appendix III

$g_i$  Linear in Each of Three Segments

If

$$\left. \begin{aligned} g_i &= a_0 + a_1x \quad (0 \leq x < X_1), \\ &= b_0 + b_1x \quad (X_1 \leq x < X_2), \\ &= c_0 + c_1x \quad (X_2 \leq x \leq 1) \end{aligned} \right\}$$

we put  $a_2 = b_2 = c_2 = k_2 = l_2 = 0$  in eqns. (49) - (56) of §5.

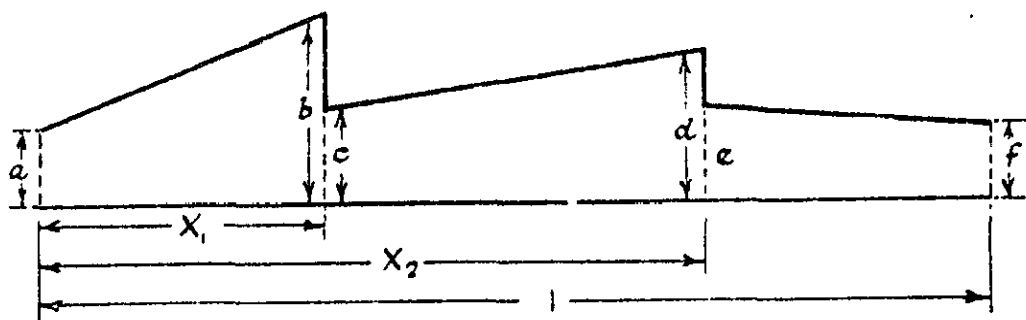
If  $g_i$  has the values shown in Fig. 1, then

$$\begin{aligned} a_0 &= a, & a_1 &= (b - a)/X_1, \\ b_0 &= \frac{b X_2 - d X_1 - (b-c)X_2}{X_2 - X_1}, & b_1 &= \frac{d - b + (b-c)}{X_2 - X_1} \\ c_0 &= \frac{d - f X_2 - (d-e)}{1 - X_2}, & c_1 &= \frac{f - d + (d-e)}{1 - X_2}. \end{aligned}$$

If  $b = c$  (Fig. 2) or  $d = e$  (Fig. 3),  $g_i$  has only one discontinuity; if  $b = c$  and  $d = e$  (Fig. 4),  $g_i$  is continuous.

For the general case of Fig. 1,

Fig. 1.



$g_i(x)/$

$$\begin{aligned}
 g_i(x) &= a \left( 1 - \frac{x}{X_1} \right) + b \frac{x}{X_1} \quad (0 \leq x \leq X_1), \\
 &= \frac{b}{X_2 - X_1} (X_2 - x) + \frac{d}{X_2 - X_1} (x - X_1) - \frac{b - c}{X_2 - X_1} (X_2 - x) \quad (X_1 \leq x \leq X_2), \\
 &= \frac{d}{1 - X_2} (1 - x) + \frac{f}{1 - X_2} (x - X_2) - \frac{d - e}{1 - X_2} (1 - x) \quad (X_2 \leq x \leq 1);
 \end{aligned}$$

$$\begin{aligned}
 G_i(x) &= a \left( x - \frac{x^2}{2X_1} \right) + b \frac{x^2}{2X_1} \quad (0 \leq x \leq X_1), \\
 &= a \frac{X_1}{2} \frac{b}{2(X_2 - X_1)} \left[ X_1 X_2 - 2X_2 x + x^2 \right] + \frac{d}{2(X_2 - X_1)} (x - X_1)^2 \\
 &\quad + \frac{b - c}{2(X_2 - X_1)} (x - X_1)(x - 2X_2 + X_1) \quad (X_1 \leq x \leq X_2), \\
 &= a \frac{X_1}{2} + b \frac{X_2}{2} - \frac{d}{2(1 - X_2)} \left[ X_1 + X_2 - X_1 X_2 - 2x + x^2 \right] + \frac{f}{2(1 - X_2)} (x - X_2)^2 \\
 &\quad - (b - c) \frac{X_2 - X_1}{2} + \frac{d - e}{2(1 - X_2)} (2X_2 - X_2^2 - 2x + x^2) \quad (X_2 \leq x \leq 1);
 \end{aligned}$$

$$\begin{aligned}
 A_1 &= \frac{4}{\pi} G_i(1) = \frac{4}{\pi} \left\{ a \frac{X_1}{2} + b \frac{X_2}{2} + d \left( \frac{1 - X_1}{2} \right) + f \left( \frac{1 - X_2}{2} \right) \right. \\
 &\quad \left. - (b - c) \left( \frac{X_2 - X_1}{2} \right) - (d - e) \left( \frac{1 - X_2}{2} \right) \right\};
 \end{aligned}$$

A<sub>0</sub>/

$$\begin{aligned}
 A_0 = & -\frac{1}{\pi} \left\{ a \left[ -\frac{(1-X_1)^2}{2X_1} \ln(1-X_1) + \frac{X_1}{2} \ln X_1 - \frac{1}{2} \right] \right. \\
 & + b \left[ \frac{X_2(1-X_1)^2}{2X_1(X_2-X_1)} \ln(1-X_1) - \frac{(1-X_2)^2}{2(X_2-X_1)} \ln(1-X_2) - \frac{X_1 X_2}{2(X_2-X_1)} \ln X_1 \right. \\
 & + \left. \frac{X_2^2}{2(X_2-X_1)} \ln X_2 \right] + d \left[ -\frac{(1-X_1)^2}{2(X_2-X_1)} \ln(1-X_1) + \frac{(1-X_1)(1-X_2)}{2(X_2-X_1)} \ln(1-X_2) \right. \\
 & + \left. \frac{X_1^2}{2(X_2-X_1)} \ln X_1 - \frac{X_2^2(1-X_1)}{2(1-X_2)(X_2-X_1)} \ln X_2 \right] \\
 & + f \left[ -\frac{1-X_2}{2} \ln(1-X_2) + \frac{X_2^2}{2(1-X_2)} \ln X_2 + \frac{1}{2} \right] \\
 & + (b-c) \left[ \frac{(1-X_1)(2X_2-1-X_1)}{2(X_2-X_1)} \ln(1-X_1) + \frac{(1-X_2)^2}{2(X_2-X_1)} \ln(1-X_2) \right. \\
 & + \left. \frac{X_1(2X_2-X_1)}{2(X_2-X_1)} \ln X_1 - \frac{X_2^2}{2(X_2-X_1)} \ln X_2 + \frac{1}{2} \right] \\
 & + (d-e) \left[ \frac{1}{2}(1-X_2) \ln(1-X_2) + \frac{X_2(2-X_2)}{2(1-X_2)} \ln X_2 + \frac{1}{2} \right] \Big\} ;
 \end{aligned}$$

$$y_c = a\eta_1 + b\eta_2 + d\eta_3 + f\eta_4 + (b-c)\eta_5 + (d-e)\eta_6,$$

where

$$\begin{aligned}
 \pi\eta_1 = & -\frac{(x-X_1)^2}{2X_1} \ln|x-X_1| - \left( x - \frac{x^2}{2X_1} \right) \ln x \\
 & + \left[ \frac{(1-X_1)^2}{2X_1} \ln(1-X_1) \right] x + \left[ \frac{X_1}{2} \ln X_1 \right] (1-x),
 \end{aligned}$$

$$\pi\eta_2 = \frac{X_2(x-X_1)^2}{2X_1(X_2-X_1)} \ln |x-X_1| - \frac{(x-X_2)^2}{2(X_2-X_1)} \ln |x-X_2| - \frac{x^2}{2X_1} \ln x$$

$$- \left[ \frac{X_2(1-X_1)^2}{2X_1(X_2-X_1)} \ln (1-X_1) - \frac{(1-X_2)^2}{2(X_2-X_1)} \ln (1-X_2) \right] x$$

$$- \left[ \frac{X_1X_2}{2(X_2-X_1)} \ln X_1 - \frac{X_2^2}{2(X_2-X_1)} \ln X_2 \right] (1-x),$$

$$\pi\eta_3 = - \frac{(x-X_1)^2}{2(X_2-X_1)} \ln |x-X_1| + \frac{(1-X_1)(x-X_2)^2}{2(1-X_2)(X_2-X_1)} \ln |x-X_2| - \frac{(1-x)^2}{2(1-X_2)} \ln(1-x)$$

$$+ \left[ \frac{(1-X_1)^2}{2(X_2-X_1)} \ln (1-X_1) - \frac{(1-X_1)(1-X_2)}{2(X_2-X_1)} \ln (1-X_2) \right] x$$

$$+ \left[ \frac{X_1^2}{2(X_2-X_1)} \ln X_1 - \frac{X_2^2(1-X_1)}{2(1-X_2)(X_2-X_1)} \ln X_2 \right] (1-x),$$

$$\pi\eta_4 = - \frac{(x-X_2)^2}{2(1-X_2)} \ln |x-X_2| + \frac{(1-x)(2X_2-1-x)}{2(1-X_2)} \ln (1-x)$$

$$+ \left[ \frac{1-X_2}{2} \ln (1-X_2) \right] x + \left[ \frac{X_2^2}{2(1-X_2)} \ln X_2 \right] (1-x),$$

$$\pi\eta_5 = \frac{(x-X_1)(2X_2-X_1-x)}{2(X_2-X_1)} \ln |x-X_1| + \frac{(x-X_2)^2}{2(X_2-X_1)} \ln |x-X_2|$$

$$- \left[ \frac{(1-X_1)(2X_2-X_1-1)}{2(X_2-X_1)} \ln (1-X_1) + \frac{(1-X_2)^2}{2(X_2-X_1)} \ln (1-X_2) \right] x$$

$$+ \left[ \frac{X_1(2X_2-X_1)}{2(X_2-X_1)} \ln X_1 - \frac{X_2^2}{2(X_2-X_1)} \ln X_2 \right] (1-x),$$

$$\pi\eta_6 = \frac{(x-X_2)(2-X_2-x)}{2(1-X_2)} \ln |x-X_2| + \frac{(1-x)^2}{2(1-X_2)} \ln (1-x)$$

$$- \left[ \frac{1}{2}(1-X_2) \ln (1-X_2) \right] x + \left[ \frac{X_2(2-X_2)}{2(1-X_2)} \ln X_2 \right] (1-x);$$

$\frac{dy_c}{dx}$

$$\frac{dy_c}{dx} - A_0 = a\xi_1 + b\xi_2 + d\xi_3 + f\xi_4 + (b-c)\xi_5 + (d-e)\xi_6,$$

where

$$\pi\xi_1 = -\frac{x-X_1}{X_1} \ln |x-X_1| + \frac{x-X_1}{X_1} \ln x - 1,$$

$$\pi\xi_2 = \frac{X_2(x-X_1)}{X_1(X_2-X_1)} \ln |x-X_1| - \frac{x-X_2}{X_2-X_1} \ln |x-X_2| - \frac{x}{X_1} \ln x,$$

$$\pi\xi_3 = -\frac{(x-X_1)}{X_2-X_1} \ln |x-X_1| + \frac{(1-X_1)(x-X_2)}{(1-X_2)(X_2-X_1)} \ln |x-X_2| + \frac{1-x}{1-X_2} \ln (1-x),$$

$$\pi\xi_4 = -\frac{x-X_2}{1-X_2} \ln |x-X_2| + \frac{x-X_2}{1-X_2} \ln (1-x) + 1,$$

$$\pi\xi_5 = -\frac{x-X_2}{X_2-X_1} \ln |x-X_1| + \frac{x-X_2}{X_2-X_1} \ln |x-X_2| + 1,$$

$$\pi\xi_6 = \frac{1-x}{1-X_2} \ln |x-X_2| - \frac{1-x}{1-X_2} \ln (1-x) + 1;$$

and

$$-C_{M_0} = \frac{1}{6} \left\{ aX_1(4X_1-3) + bX_2(4X_1+4X_2-3) + d(1-X_1)(4X_1+4X_2+1) \right. \\ \left. + f(1-X_2)(4X_2+5) - (b-c)(X_2-X_1)(4X_2+8X_1-3) - (d-e)(1-X_2)(1+8X_2) \right\}$$

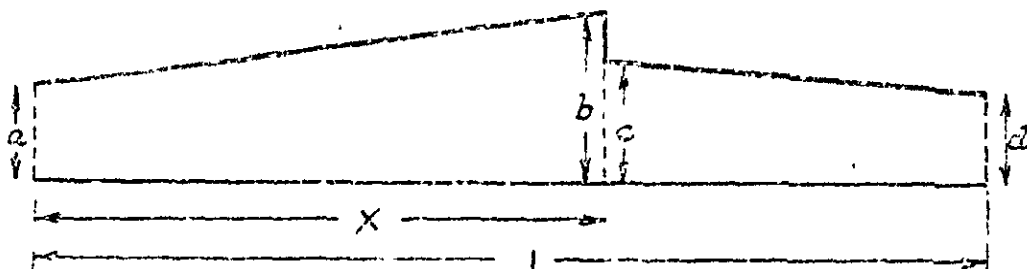
For  $\beta$ ,  $\varepsilon_c(0)$ ,  $C_{Lopt}$ ,  $\alpha_{opt}$ ,  $\varepsilon_c(\theta)$ ,  $\varepsilon_c'(\theta)$  see eqns. (6), (8), (9), (27) and (28).

$\xi_1/$

$g_i$  Linear in Each of Two Segments

If  $g_i$  is linear in each of two segments,  $0 < x < X$ ,  $X < x < 1$ , and has the values shown in Fig. 5, then

Fig. 5



$$g_i(x) = a \left( 1 - \frac{x}{X} \right) + b \frac{x}{X} \quad (0 < x < X)$$

$$= \frac{b}{1-X} (1-x) + \frac{d}{1-X} (x-X) - \frac{b-c}{1-X} (1-x) \quad (X < x < 1).$$

We obtain the required formulae by putting  $d = e = f$ , and then making  $X_2 \rightarrow 1$ , in the results immediately preceding.

We thus obtain the following formulae.

$$G_i(x) = a \left( x - \frac{x^2}{2X} \right) + b \frac{x^2}{2X} \quad (0 < x < X),$$

$$= a \frac{X}{2} - \frac{b}{2(1-X)} \left[ X - 2x + x^2 \right] + \frac{d}{2(1-X)} (x-X)^2 + \frac{b-c}{2(1-X)} (x-X)(x+X-1)$$

$(X < x < 1);$

$$A_1 = \frac{4}{\pi} \left\{ a \frac{X}{2} + \frac{b}{2} + d \frac{1-X}{2} - (b-c) \left( \frac{1-X}{2} \right) \right\};$$

$A_0/$

$$\begin{aligned}
 A_0 = & -\frac{1}{\pi} \left\{ a \left[ -\frac{(1-X)^2}{2X} \ln(1-X) + \frac{X}{2} \ln X - \frac{1}{2} \right] \right. \\
 & + b \left[ \frac{1-X}{2X} \ln(1-X) - \frac{X}{2(1-X)} \ln X \right] \\
 & + d \left[ -\frac{1-X}{2} \ln(1-X) + \frac{X^2}{2(1-X)} \ln X + \frac{1}{2} \right] \\
 & \left. + (b-c) \left[ \frac{1-X}{2} \ln(1-X) + \frac{X(2-X)}{2(1-X)} \ln X + \frac{1}{2} \right] \right\};
 \end{aligned}$$

$$y_c = ah_1 + bh_2 + dh_3 + (b-c)h_4,$$

where

$h_1 = \eta_1$  (as given in the preceding section of this Appendix),

$$\begin{aligned}
 \pi h_2 = & \frac{(x-X)^2}{2X(1-X)} \ln|x-X| - \frac{(1-x)^2}{2(1-X)} \ln(1-x) - \frac{x^2}{2X} \ln x \\
 & - \left[ \frac{1-X}{2X} \ln(1-X) \right] x - \left[ \frac{X}{2(1-X)} \ln X \right] (1-x),
 \end{aligned}$$

$$\begin{aligned}
 \pi h_3 = & -\frac{(x-X)^2}{2(1-X)} \ln|x-X| - \frac{(1-x)(2X-1-x)}{2(1-X)} \ln(1-x) \\
 & + \left[ \frac{1-X}{2} \ln(1-X) \right] x + \left[ \frac{X^2}{2(1-X)} \ln X \right] (1-x),
 \end{aligned}$$

$$\begin{aligned}
 \pi h_4 = & \frac{(x-X)(2-X-x)}{2(1-X)} \ln|x-X| + \frac{(1-x)^2}{2(1-X)} \ln(1-x) - \left[ \frac{1-X}{2} \ln(1-X) \right] x \\
 & + \left[ \frac{X(2-X)}{2(1-X)} \ln X \right] (1-x);
 \end{aligned}$$

$$\frac{dy_c}{dx} - A_0 = ah_1 + bh_2 + dh_3 + (b-c)h_4,$$

where/

where

$$H_1 = \xi_1 \text{ (as given in the preceding section of this appendix),}$$

$$\pi H_2 = \frac{x-X}{X(1-X)} \ln |x-X| + \frac{1-x}{1-X} \ln (1-x) - \frac{x}{X} \ln x,$$

$$\pi H_3 = -\frac{x-X}{1-X} \ln |x-X| + \frac{x-X}{1-X} \ln (1-x) + 1,$$

$$\pi H_4 = \frac{1-x}{1-X} \ln |x-X| - \frac{1-x}{1-X} \ln (1-x) + 1;$$

$$-C_{M_0} = \frac{1}{6} \{aX(4X-3) + b(4X+1) + d(1-X)(4X+5) - (b-c)(1-X)(8X+1)\}.$$

For  $\beta$ ,  $\varepsilon_c(0)$ ,  $C_{Lopt}$ ,  $\alpha_{opt}$ ,  $\varepsilon_c(\theta)$ ,  $\varepsilon_c'(\theta)$  see eqns. (6), (8), (9), (27) and (28).

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AH.





C.P. No.71  
(8548)  
A.R.C. Technical Report

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