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A Note on the Estimation of the Effect of
Wind Tunnel Walls on the Forces
on Slowly Oscillating Slender Wings

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A Note on the Estimation of the Effect of Wind Tunnel Walls
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- By -
W. E. A. Acum

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1. Introduction

The formulae for tunnel interference upwash on small wings performing slow oscillations in closed rectangular or circular wind tunnels were derived some years ago (Refs.1 and 2). A "small wing" is one whose cross-stream and streamwise dimensions are all small compared with those of the tunnel cross section; such a "small wing" is in fact merely an element of area with its associated lift, and, within the assumptions of linearised theory, any wing may be regarded as made up of such lifting elements. In particular a slender wing on the tunnel axis is equivalent to a streamwise row of small wings, and this leads to a very simple method for calculating the interference upwash on a slender wing. As given the theory is for incompressible flow, but subsonic compressibility effects may be introduced by a minor alteration.

It must be observed that, besides the fact that the wing is slender, it is assumed that the frequency parameter of the oscillation is small and that the streamwise extent of the wing is small enough for the interference upwash to be regarded as varying linearly over the length of the wing. Moreover, the mean position of the wing is assumed to lie on the tunnel axis. Although the theory thus appears to be severely restricted these conditions are likely to be satisfied in a significant number of experiments.

2. Notation

A	aspect ratio of wing
b	breadth of rectangular tunnel
C_L	theoretical lift coefficient, $Lift/(\frac{1}{2}\rho U^2 S)$
C'_L	measured value of C_L
δC_L	tunnel induced increment in C_L
C_m	theoretical pitching moment coefficient, (nose up pitching moment)/ $(\frac{1}{2}\rho U^2 S \bar{c})$

$C'_m /$

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C'_m	measured value of C_m
δC_m	tunnel induced increment to C_m
c_r	root chord of wing
\bar{c}	mean chord of wing
h	height of rectangular tunnel
L	lift force per unit streamwise distance
l	local lift coefficient, (local lift per unit area)/($\frac{1}{2}\rho U^2$)
M	Mach number
S	area of planform
$s(x)$	local semi-span
t	time
U	undisturbed wind velocity
w	component of flow velocity in the z direction ("upwash")
w_i	tunnel-induced upwash
x, y, z	rectangular co-ordinates
x_o	value of x at pitching axis
β	$(1 - M^2)^{\frac{1}{2}}$
$\theta = \theta_o e^{i\omega t}$	angle of incidence
\bar{v}	frequency parameter, $\omega\bar{c}/U$
ρ	density
ω	angular frequency of oscillation

3. Interference Upwash due to a Slender Wing in a Rectangular Tunnel

Consider a wind tunnel of closed rectangular section of height h , and breadth b , composed of solid surfaces in the planes $y = \pm\frac{1}{2}h$, and $z = \pm\frac{1}{2}b$ and extending from $x = -\infty$ to $x = +\infty$, where x, y, z is a rectangular co-ordinate system. Now consider a wing performing harmonic oscillations but lying at all times near to the plane $z = 0$. According to linearised theory the total interference upwash is the sum of the interference upwashes due to each of the lifting elements into which the wing may be divided. In particular, if the wing is slender, it may be divided into a large number of

small/

small elements by planes $x = \xi$; the element lying between $x = \xi$ and $x = \xi + \delta\xi$ will, since the span is small, have dimensions small compared with the cross-section of the tunnel, and may therefore be treated by the theory for small wings given in Ref.1 or the appendix to Ref.2. Thus the interference upwash caused by a slowly oscillating small wing at the origin is

$$\frac{w_1(x,0,0)}{U} = \frac{SC_L}{bh} \left\{ \delta_0 + \frac{x \delta_1}{h} + \frac{i\omega h}{U} \left[\delta'_0 + \frac{x \delta'_1}{h} \right] \right\} + O\left(\frac{x}{h}\right)^2 \quad \dots (1)$$

where δ_0 , δ_1 , δ'_0 and δ'_1 are constants depending on the shape of the tunnel, b/h . Tables of $\delta_0, \dots, \delta'_1$ may be found in Ref.2. It is assumed that $\omega h/U$ and x/h are small. Equation (1) applies to incompressible flow, but compressibility may be accounted for by replacing δ_1 in equation (1) by δ_1/β and δ'_0 by δ'_0/β , where $\beta = (1 - M^2)^{\frac{1}{2}}$.

When applied to that part of the slender wing between $x = \xi$ and $x = \xi + \delta\xi$ equation (1) becomes

$$\frac{\delta w_1(x,0,0)}{U} = \frac{1}{bh} \left[\int_{-s(\xi)}^{s(\xi)} \ell(\xi, y) dy \right] \cdot \left[\delta_0 + \frac{(x-\xi)\delta_1}{h} + \frac{i\omega h}{U} \left(\delta'_0 + \frac{(x-\xi)\delta'_1}{h} \right) \right] \delta\xi \quad \dots (2)$$

The total interference upwash follows by integration

$$\frac{w_1(x,0,0)}{U} = \frac{S}{bh} \left[C_L \left\{ \delta_0 + \frac{x \delta_1}{h} + \frac{i\omega h}{U} \left(\delta'_0 + \frac{x \delta'_1}{h} \right) \right\} + C_m \frac{\bar{c}}{h} \left\{ \delta_1 + \frac{i\omega h \delta'_1}{U} \right\} \right] \quad \dots (3)$$

In equation (3) C_m refers to the pitching moment about $x = 0$.

The behaviour of w_1/U when x is not small is considered briefly in the Appendix.

When the flow is steady it is possible to use the more elaborate formula derived by Berndt³ for slender wings in rectangular tunnels. In Berndt's expression corresponding to equation (1) ω is, of course, zero, and it is not assumed that w_1 is linear in x .

4. Calculation of Interference Forces

In equation (3) w_i is the additional upwash caused by the presence of the tunnel walls. In fact the upwash at the wing is dictated by its mode of oscillation, and we may therefore regard the tunnel walls as supplying w_i towards the total upwash, thus reducing by w_i the part to be supplied by the lift distribution over the wing. The incremental forces due to the tunnel interference are therefore obtained from linearised theory by taking the prescribed upwash at the wing as $-w_i$.

From the formulae of slender wing theory (Ref.4) the lift per unit length in the x direction is given by

$$L(x) = -\pi\rho U^2 \left\{ s^2 \left[\frac{\partial}{\partial x} + \frac{i\omega}{U} \right] \frac{w}{U} + 2s \frac{ds}{dx} \frac{w}{U} \right\}, \quad \dots (4)$$

where w is the upwash prescribed by the motion of the wing. Equation (4) may be used to calculate the incremental lift due to tunnel interference by taking w/U equal to $-w_i/U$ as given by equation (3).

In the absence of direct experimental values, or more accurate theoretical values, the complex quantities C_L and C_m in equation (3) may also be estimated by (4).

5. Tunnels of Other Cross Sections

Values of δ_0 , δ_1 , δ'_0 and δ'_1 for a small wing on the axis of a closed circular tunnel are given in Ref.2. Equation (1) is unchanged except that h , taken as the typical length in (1), must be replaced by the diameter, and bh replaced by the area of cross section of the circular tunnel.

For the circular tunnel Goodman⁵ has extended equation (1) to cover all frequency parameters and streamwise positions, but the equation for w_i is naturally more complicated and the integration leading to equation (3) would no longer be so simple.

6. Example

Consider a slender triangular wing pitching about an axis through its in-phase centre of pressure, in a low-speed tunnel for which $b/h = 9/7$. The length of the root-chord, c_r , will be assumed to be equal to the tunnel height, h . The aspect ratio, A , will be assumed small but otherwise left unspecified. Denote the pitching axis by $x = x_0$. Then the equation of the wing surface is

$z/$

$$z = -\theta_0 e^{i\omega t} (x - x_0), \quad \dots (5)$$

and the upwash angle at the wing is therefore

$$\frac{w}{U} = -\theta_0 e^{i\omega t} \left[1 + \frac{i\omega(x - x_0)}{U} \right]. \quad \dots (6)$$

For a delta wing take the origin of co-ordinates at the apex so that $s(x) = Ax/4$. Then substitution in equation (4) yields the following approximate theoretical lift and pitching moment,

$$\left. \begin{aligned} C_L &= \frac{\pi A}{2} \theta_0 e^{i\omega t} \left[1 + \frac{i\omega c_r}{U} \left(\frac{4}{3} - \frac{x_0}{c_r} \right) \right], \\ C_m &= -\pi A \theta_0 e^{i\omega t} \left[\frac{2}{3} + \frac{i\omega c_r}{U} \left(1 - \frac{2x_0}{3c_r} \right) \right], \end{aligned} \right\} \dots (7)$$

where C_m is referred to $x = 0$.

It follows that the in-phase centre of pressure is at $x = 4\bar{c}/3$, so that $x_0 = 4\bar{c}/3 = 2c_r/3$, and equations (7) become

$$\left. \begin{aligned} C_L &= \pi A \theta_0 e^{i\omega t} \left[\frac{1}{2} + \frac{1}{3} \frac{i\omega c_r}{U} \right], \\ C_m &= -\pi A \theta_0 e^{i\omega t} \left[\frac{2}{3} + \frac{5}{9} \frac{i\omega c_r}{U} \right]. \end{aligned} \right\} \dots (8)$$

Now from Table AII of Ref.2, for $b/h = 9/7$

$$\left. \begin{aligned} \delta_0 &= 0.120\ 390, \\ \delta_1 &= 0.228\ 247, \\ \delta'_0 &= -0.020\ 224, \\ \delta'_1 &= -0.120\ 390. \end{aligned} \right\} \dots (9)$$

It has been assumed that $h = 2\bar{c} = c_r$, so that $b = 9h/7 = 18\bar{c}/7$, and for delta wings $S = \bar{A}\bar{c}^2$. Then from equations (3) and (9)

$$\frac{w_i}{U} = \frac{7A}{36} \left[C_L \left\{ \left(0.120390 + 0.114124 \frac{x}{c} \right) - i\bar{\nu} \left(0.040448 + 0.120390 \frac{x}{c} \right) \right\} + C_m \left\{ 0.114124 - i\bar{\nu} 0.120390 \right\} \right], \quad \dots (10)$$

where
$$\bar{\nu} = \frac{\omega\bar{c}}{U}, \quad \dots (11)$$

and it has been assumed that $\bar{\nu}$ is small.

From equation (4) it may be deduced that the incremental forces due to tunnel interference are

$$\delta C_L = \frac{\pi A}{2} \left(\frac{w_i}{U} \right)_{x=c_r} + \frac{i\omega}{U} \frac{\pi A}{2} \frac{1}{c_r^2} \int_0^{c_r} x^2 \frac{w_i}{U} dx, \quad \dots (12)$$

and
$$\delta C_m = -\pi A \left(\frac{w_i}{U} \right)_{x=0_r} + \pi A \frac{1}{c_r^3} \int_0^{c_r} x^2 \frac{w_i}{U} dx - \frac{i\omega}{U} \pi A \frac{1}{c_r^3} \int_0^{c_r} x^3 \frac{w_i}{U} dx. \quad \dots (13)$$

Then δC_L and δC_m are obtained numerically by substituting from equations (8) into equation (10), and then from (10) into (12) and (13). After some calculation we find

$$\left. \begin{aligned} \delta C_L &= \pi A^3 \theta_0 e^{i\omega t} \{0.030004 + i\bar{\nu} 0.028053\}, \\ \text{and } \delta C_m &= -\pi A^3 \theta_0 e^{i\omega t} \{0.045815 + i\bar{\nu} 0.043130\}, \end{aligned} \right\} \dots (14)$$

where δC_m is referred to $x = 0$.

Now/

Now δC_L and δC_m are those parts of the measured lift and moment due to tunnel interference. The obvious way of applying tunnel corrections is therefore to subtract δC_L and δC_m from the measured C_L and C_m respectively; if this is done the measured values of C_L and C_m should be used in equation (3) to obtain w_1 .

Alternatively the correction may be regarded primarily as one to incidence with a residual correction to pitching moment. Let the measured values of C_L and C_m be C'_L and C'_m while undashed symbols represent theoretical estimates. Thus from the method described in Ref.1 the correction to be added to the incidence is

$$\Delta\theta = C'_L \frac{\partial \delta C_L}{\partial \theta} \bigg/ \left(\frac{\partial C_L}{\partial \theta} \right)^2, \quad \dots (15)$$

with a residual correction to pitching moment

$$\Delta C_m = (C'_m)_{\text{corrected}} - (C'_m)_{\text{measured}} = \frac{C'_L}{\left(\frac{\partial C_L}{\partial \theta} \right)^2} \left\{ \frac{\partial C_m}{\partial \theta} \frac{\partial \delta C_L}{\partial \theta} - \frac{\partial C_L}{\partial \theta} \frac{\partial \delta C_m}{\partial \theta} \right\}. \quad \dots (16)$$

The suffices L and m may be interchanged throughout equations (15) and (16), that is the correction to incidence may be made to depend on pitching moment. This has to be done if only C'_m is measured.

Up to this point it has been assumed that the pitching moments are taken about $x = 0$; it is more usual to refer them to the pitching axis. This does not affect the form of equation (15), nor, in fact, does a change of axis which is the same for both C_m and δC_m , alter the value of ΔC_m . In the present example, a triangular wing, it was assumed that $x_0 = 4\bar{0}/3$, and the theoretical tunnel induced and free-stream pitching moments referred to this axis are

$$\delta C_m = -\pi A^3 \theta_0 e^{i\omega t} [0.005810 + i\bar{v} 0.005726], \quad \dots (17)$$

$$C_m = -\pi A \theta_0 e^{i\omega t} \frac{2}{9} i\bar{v} \quad \dots (18)$$

while/

while δC_L and C_L are, of course, unchanged. Then, from the first of equations (8), the first of equations (14), and equation (15), it follows that

$$\Delta\theta = C_L^i A (0.038202 - i\bar{v} 0.066155) , \quad \dots (19)$$

and from equations (17), (18) and (16) that

$$\Delta C_m = C_L^i A (0.01162 - i\bar{v} 0.01909) . \quad \dots (20)$$

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APPENDIX

The Variation of Interference Upwash with Streamwise Distance
for Small Wings in Rectangular Tunnels

From the treatment of the small wing given in Ref.1 it follows that the interference upwash for such a wing in a rectangular tunnel is

$$\frac{w_1(x,0,0)}{U} = \frac{SC_L}{2b^2} \left[F_2(\xi,0) - \frac{i\omega b}{U} \exp\left(\frac{-i\omega x}{U}\right) \int_{-\infty}^{x/b} \exp\left(\frac{i\omega b \theta}{U}\right) F_2(\theta,0) d\theta \right], \quad \dots (A.1)$$

$$\text{where } F_2(\xi,0) = \frac{-b^2}{4\pi h^2} \sum_{m=-\infty}^{m=+\infty} \sum_{n=-\infty}^{n=+\infty} (-1)^n \left[\frac{n^2 - Y^2}{(n^2 + Y^2)^2} \left(1 + \frac{X}{\sqrt{X^2 + Y^2 + n^2}}\right) + \frac{n^2}{Y^2 + n^2} \frac{X}{(X^2 + Y^2 + n^2)^{3/2}} \right], \quad \dots (A.2)$$

where $X = b\xi/h$, $Y = mb/h$, and the term in $m = n = 0$ is omitted from the double summation.

For small x expansion of equation (A.2) as a power series in x gives

$$F_2(\xi,0) = \frac{-b^2}{4\pi h^2} \sum_{m=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} (-1)^n \left[\frac{n^2 - Y^2}{(n^2 + Y^2)^2} + \frac{x}{h} \frac{2n^2 - Y^2}{(n^2 + Y^2)^{5/2}} - \frac{x^2}{h^2} \frac{2n^2 - \frac{1}{2}Y^2}{(n^2 + Y^2)^{7/2}} + \dots \right], \quad \dots (A.3)$$

provided x is less than the smaller of b or h . The first two terms lead to δ_0 and δ_1 , which are already known, but obviously higher terms could be included. If $\omega b/U$ is small the second term in the right-hand side of equation (A.1) may be replaced by

$$-\frac{i\omega b}{U}$$

$$\begin{aligned}
 & - \frac{i\omega b}{U} \int_{-\infty}^{x/b} F_2(\theta, 0) d\theta \\
 = & \frac{i\omega b}{U} \frac{b}{4\pi h} \sum_{m=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} (-1)^n \left[\frac{n^2 - Y^2}{(n^2 + Y^2)^2} \left(\frac{x}{h} + \sqrt{\left(\frac{x}{h}\right)^2 + Y^2 + n^2} \right) \right. \\
 & \left. - \frac{n^2}{n^2 + Y^2} \frac{1}{\sqrt{\left(\frac{x}{h}\right)^2 + Y^2 + n^2}} \right], \\
 = & \frac{i\omega h}{U} \frac{b^2}{4\pi h^2} \sum_{m=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} (-1)^n \left[\frac{-Y^2}{(n^2 + Y^2)^{3/2}} + \frac{x}{h} \frac{n^2 - Y^2}{(n^2 + Y^2)^2} + O\left(\frac{x^3}{h^3}\right) \right].
 \end{aligned}$$

... (A.4)

From a comparison of equations (A.3) and (A.4) with equation (1), it follows that

$$\left. \begin{aligned}
 \delta_0 = -\delta_1' &= -\frac{1}{8\pi} \frac{b}{h} \sum_{m=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} (-1)^n \frac{n^2 - m^2 b^2/h^2}{(n^2 + m^2 b^2/h^2)^2}, \\
 \delta_1 &= -\frac{1}{8\pi} \frac{b}{h} \sum_{m=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} (-1)^n \frac{2n^2 - m^2 b^2/h^2}{(n^2 + m^2 b^2/h^2)^{3/2}}, \\
 \delta_0' &= -\frac{1}{8\pi} \frac{b}{h} \sum_{m=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} (-1)^n \frac{m^2 b^2/h^2}{(n^2 + m^2 b^2/h^2)^{3/2}},
 \end{aligned} \right\} \dots (A.5)$$

In the double summations the term $m = n = 0$ is to be omitted.

The series for δ_0 and δ_1 are the well-known sums for a small wing in steady flow. The double series for δ_0' is not convergent; it does give a sum if summed first with respect to n and then with respect to m ,

and/

and this sum is the same as that obtained by a numerical integration of

$$\int_{-\infty}^0 \mathbb{F}_p(\theta, 0) d\theta, \text{ and is therefore, as it happens, correct.}$$

The coefficients of higher powers of x/h depend on sums of the type

$$\sum_{m=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} (-1)^n \frac{c_1 n^2 + c_2 m^2 b^2 / h^2}{[n^2 + m^2 b^2 / h^2]^{p+1/2}} \dots (A.6)$$

where p is an integer and c_1 and c_2 are constants.

Now consider

$$S_p(x) = \sum_{n=-\infty}^{\infty} (-1)^n \frac{x}{(n^2 + x^2)^{p+1/2}} \dots (A.7)$$

By Poisson's formula (Ref.6) if $f(x)$ is continuous and of bounded variation

in $0 \leq x < \infty$, f tends to zero as x tends to infinity, and $\int_0^{\infty} f(t) dt$ exists then

$$\frac{1}{2} f(0) + \sum_{n=1}^{\infty} f(n) = \int_0^{\infty} f(t) dt + 2 \sum_{n=1}^{\infty} \int_0^{\infty} f(t) \cos 2\pi n t dt \dots (A.8)$$

To apply this to S_p take

$$f(n) = \frac{\cos \pi n \cdot x}{(n^2 + x^2)^{p+1/2}}, \dots (A.9)$$

so that

$$\int_0^{\infty} \dots$$

$$\int_0^\infty f(t) \cos 2\pi nt \, dt = \int_0^\infty \frac{\cos 2\pi nt \cos \pi t \cdot x}{(t^2 + x^2)^{p+\frac{1}{2}}} \, dt, \quad \dots (A.10)$$

and it follows that

$$S_p(x) = 4x \sum_{n=1}^\infty \int_0^\infty \frac{\cos [(2n-1)\pi t]}{(t^2 + x^2)^{p+\frac{1}{2}}} \, dt. \quad \dots (A.11)$$

The integrals in this summation may be expressed as Bessel functions (Ref.7) and it follows that

$$S_p(x) = \frac{2\pi^p}{(2x)^{p-1}} \frac{\Gamma(\frac{1}{2})}{\Gamma(p+\frac{1}{2})} \sum_{n=1}^\infty (2n-1)^p K_p((2n-1)\pi x). \quad \dots (A.12)$$

This transformed series is rapidly convergent unless x is small. If x is small and positive,

$$S_p(x) = \frac{1}{x^p} + 2 \sum_{n=1}^\infty \frac{(-1)^n}{n^{2p+1}} x$$

$$- (2p+1) \sum_{n=1}^\infty \frac{(-1)^n}{n^{2p+3}} x^3 + \frac{(2p+1)(2p-1)}{2} \sum_{n=1}^\infty \frac{(-1)^n}{n^{2p+5}} x^5$$

- (A.13)

Thus $S_p(x)$ is easily calculated for all x , and equation (A.12) shows that it tends to zero exponentially as x tends to infinity. Thus sums of the form (A.6) are also easily evaluated. The treatment when the factor $(-1)^n$ is omitted from equation (A.7) is analogous.

DR

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